

Automation for a Changing World

Delta Vector Control Drive C2000 Series







Powerful Features. High Efficiency

The C2000 series AC motor drive provides the most efficient and cost-effective solution for all types of drive applications. It features precise speed, torque and position control functions that are suitable for both sensor and sensorless types of synchronous and asynchronous motors. The C2000 series is also equipped with built-in PLC functions and supports the CANopen Master/Slave extension for the ultimate in system flexibility and fast data exchange.

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Permanent magne	et motors (SPM, IPM)	

- Permanent magnet motors (SPM, IPM) REG2000 Series AFE2000 Series
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Standard Models (IP20/NEMA1)

Power range: 230V 0.75~90kW, 460V 0.75~450kW

230V (kW)	0.75	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30	37	45	55	75	90	
230V (HP)	1	2	3	5	7.5	10	15	20	25	30	40	50	60	75	100	125	
Frame Size		ļ	4			В			С		[)		Е		F	
Braking Chopper					Bui	lt-in							Opti	onal			
DC Reactor					Opti	onal							Bui	lt-in			
EMI Filter								Opti	onal								
Protection Level					IP	20							IP00	/ IP20			
460V (kW)	0.75	1.5	2.2	3.7	4.0	5.5	7.5	11	15	18.5	22	30	37	45	55	75	90
460V (HP)	1	2	3	5	5	7.5	10	15	20	25	30	40	50	60	75	100	125
Frame Size			ļ	4				В			С		D	0	I)	
Braking Chopper	Built-in																
DC Reactor	Optional																
EMI Filter	Built-in (VFDC43E)																
Protection Level		IP20															

*Available in China and Taiwan only.

Advanced Drive Controls

Door Width Auto-tuning

- 1. High bandwidth control
- 2. Speed/torque/position control mode
- 3. Dual rating design (Normal duty/heavy duty)
- 4. 4-quadrant torque control and limit
- 5. For both synchronous and
- asynchronous motors

Environmental Adaptability

- 1. 50°C operating temperature
- 2. Built-in DC reactor
- 3. Coated circuit boards
- 4. Built-in EMI filter
- 5. Global safety standards (CE/UL/cUL)

*Note: Please refer to the Product Specification



110	132	160	185	220	280	315	355	450 *
150	175	215	250	300	375	425	475	600
	F	-	(3		ŀ	-	
	Opti	onal						
	Bui	lt-in						
	Opti	onal						
	IP00	/ IP20						

Versatile Drive Controls

- 1. Built-in safe stop function
- 2. Built-in PLC function
- 3. Built-in brake unit
- 4. Supports various network protocols
- 5. Synchronous point-to-point control

Modular Design

- 1. Hot plug LCD keypad
- 2. I/O extension cards
- 3. Various PG (encoder) feedback cards
- 4. Network cards for fieldbus modules
- 5. Removable fan





Modular Design

Various accessories options, such as I/O extension cards, encoder feedback cards, communication cards, hot plug LCD keypad, removable terminals and removable fans.



- The modular design fulfills the needs of system applications and equipment maintenance.
- KPC-CC01 keypad -
- Standard RJ45 network cable.
- Easy to remove with one press





- Remove the safety screws and press on two sides to remove the cover for wiring
- Modular fan design is easy to clean and replace providing longer service life.

The product nameplate shows

the input/output voltage,

input/output current, the frequency range, and more.



RFI Switch





Dust-proof

Excellent Environment Adaptability

- Built-in DC choke to surpress harmonics*
- Built-in EMI filter to filter noise*
- Conformal coating (Class 3C2 of IEC60721-3-3 standard) ensures drive operation stability and safety in critical environments.
- The electronic components of the drive are isolated from the cooling system to reduce heat interference. Dissipated heat can be discharged by flange-mounting installation, and forced fan cooling can import cold air into the heat sink. The heat dissipation performance is optimized by these two cooling methods.
 "Note: Please refer to the Product Specification



Certifications

UL, cUL	CE
C-Tick	Low Voltage: EN61800-5-1
ROHS	EMC: EN61000-3-12, EN61800-3, IEC61000-6-2, IEC61000-6-4, IEC61000-4-2, IEC61000-4-3, IEC61000-4-4, IEC61000-4-5, IEC61000-4-6, IEC61000-4-8,



Quick and easy parameters setting via the LCD keypad

- Multi-column display for the drive status
- Simple and intuitive operation
- User-defined parameter groups
- Real Time Clock and calendar function
- Language selection for display
- Copy function saves parameters and PLC programs to the keypad memory for later transfer to another drive
- IP66 protection level





Create homepage logo



Editable message display



Editable chart display

Intelligent PLC Functions

- Built-in 10K steps capacity of PLC functions. Distributed control and independent operation are easily achieved via network connection.
- CANopen Master protocol and PLC functions provide synchronous control and fast data exchange.



High-speed Network

- Provides optional MODBUS RTU and various fieldbus cards for flexible communication applications
- Advanced network functions
- Built-in MODBUS communication interface
- CANopen (DS402)



- Ability to control up to 8 Slave drives via the CANopen Master function
- · Supports all Delta industrial automation products · TAP-CN03 distribution (all EDS files of Delta industrial automation products are built-in) box for long distances · I/O data layout of each piece of equipment on the **CANopen Network** Planning function for motion control CANOOR CANODEr WPL Soft RJ45 cable 1Mbps 25m 500kbps 100m FtherNet DeviceN Delta DeviceNet Builder software is specially designed for MODBUS TCP DeviceNet communication. With this software, it is easy to Delta's communication integrator software not only provides graphic plan DeviceNet equipment and remote I/O via parameters to module setting and a human interface design but also supports build a standard DeviceNet monitoring structure. settings and online monitoring for all Ethernet products. · Supports all Delta industrial automation products Delta software for (all EDS files of Delta Ethernet/MODBUS TCP industrial automation products products are built-in) Graphic module I/O data layout of setting and human each piece of THE H II II II interface design equipment in the · Auto search function DeviceNet network Setting interface for DeviceNet Builder DeviceNet layout virtual COM port
 - software



Convenient Operation Platform for Drive System Management

Provides a complete operation platform for users' easy control and monitoring via PC, including parameters save/setting, real-time wave monitor, quick setup, for multiple languages and with multi-language operation systems.



High-performance Field Oriented Control

The FOC+PG mode of C2000 series can output 150% of starting torque at extremely low speeds for precise and stable speed control.



Fast Response to Impact Load

During load changes, the VFD-C2000 calculates the required torque response and minimizes the vibration caused by load impact using FOC.



Precise position and speed control ideal for printing machine applications.



Auto Energy-Saving Operation

During constant speed operation, this function auto-calculates the best voltage value by the load power for the load.



Deceleration Energy Backup (dEB)

This function controls the motor deceleration for stopping when an unexpected power shut down occurs to prevent mechanical damage. When power resumes, the motor will return to its previous speed.





A Drive for Permanent Magnet (PM) Motors

The C2000 is a dual mode drive to control both an induction motor and permanent magnet motor. The dynamic response of a PM motor provides precise control of position, speed and torque.



Delta REG2000 Series for Power Regeneration

Using the REG2000 with the C2000 in a crane and hoist application provides the user with a four-quadrant operation and energy saving results.



Delta AFE2000 Series for Power Regeneration and Power Quality Improvement

The Active Front End Unit (AFE2000) helps to reduce torque ripple and harmonics with a higher power factor to provide excellent production quality and outstanding energy saving results.







Delta Active Front End AFE2000 Series

Features

- Replaces traditional brake resistor to reduce heat generation.
- Clear energy savings: more than 95% of the regenerative energy is converted into electricity and supplied back to the mains.
- Full-load operation: input-side current THD lower than 5% and improves power factor up to 99%.
- AC motor drives with AFE2000: supports
 4-quadrant operation with variable frequencies and adjustable system.
- Constant DC bus voltage: unaffected by mains voltage fluctuations.



Improves power factor and decreases harmonic distortion. THD<=5%, power factor > 99%



Improves power factor by 20%



Applications

- Large-inertia loads, such as centrifuge equipment, dewatering machines and roving machines
- 4-quadrant loads including elevators, cranes and pumpjacks (oil extraction machines)
- Quick braking, such as machine tools, bag making machines, auto storage and retrieval systems, and lathes
- Long-term energy feedback, such as wind power, water power, steel printing and paper making machinery (winding equipment)
- Improves power quality for industries such as semiconductor and panel industries







Operating Environment

DO NOT expose the AC moto gasses, humidity, liquid or v	or drive to ha vibrations. T	rsh environments, s he salt in the air mu	such as dust, direct sunlight, corrosive/ inflammable st be less than 0.01mg/cm ² per year.							
Installation location	IEC60364-1/I	IEC60364-1/IEC60664-1 Pollution degree 2, Indoor use only								
Surrounding	Storage/ Tran	sportation	-25°C ~ +70°C							
Temperature	No condensat	tion, no frost								
	Operation		Max. 95%							
Rated Humidity	Storage/ Tran	sportation	Max. 95%							
	No condensat	tion, no frost								
Air Proceuro	Operation/ St	orage	86 to 106 kPa							
All Plessure	Transportatio	n	70 to 106 kPa							
	IEC60721-3-3	3								
	Operation		Class 3C2 ; Class 3S2							
Pollution Level	Storage		Class 2C2 ; Class 2S2							
	Transportatio	n	Class 1C2 ; Class 1S2							
	No condensat	tion, no frost								
Altitude	Operation	If AC motor drive is in: If it is install at altitude temeperature for even Grounded is 2000m.	stalled at altitude 0~1000m, follow normal operation restriction. e 1000~3000m, decrease 2% of rated current or lower 0.5°C of y 100m increase in altitude. Maximum altitude for Corner							
Package Drop	Storage/ Tran	sportation	ISTA procedure 1A(according to weight) IEC60068-2-31							
Vibration	1.0mm, peak to peak value range from 2Hz to 13.2 Hz; 0.7G~1.0G range from 13.2Hz to 55Hz; 1.0G range from 55Hz to 512 Hz. Comply with IEC 60068-2-6									
Impact	IEC/EN 60068-2-27									
Operation Position	Max. allowed (under norma	10°—, y—10°								

Specification for Operation Temperature and Protection Level

Model	Frame	Top Cover	Conduit Box	Protection Level	Operation Temperature
	Frame A~C	Remove top cover	Standard	IP20/UL Open Type	-10°C ~50°C
	460V: 0.75~30kW	Standard with top cover	conduit plate	IP20/UL Type1/NEMA1	-10°C ~40°C
VFDxxxCxxA VFDxxxCxxS	VFDxxxCxxA VFDxxxCxxS Frame D~H 230V: >22kW 460V: >30kW		No conduit box	IP00 IP20/UL Open Type IP00: for the circled area IP20: for all other area	-10°C ~50°C
	Frame A~C	Remove top cover	Standard	IP20/UL Open Type	-10°C ~50°C
VFDxxxCxxE	460V: 0.75~30kW	Standard with top cover	conduit plate	IP20/UL Type1/NEMA1	-10°C ~40°C
VFDxxxCxxU	Frame D~H 230V: >22kW 460V: >30kW	N/A	Standard conduit box	IP20/UL Type1/NEMA1	-10°C ~40°C



Specifications

2300		Frame Size		A				В			С)		E		F
	/	Model VFDC	007	015	022	037	055	075	110	150	185	220	300	370	450	550	750	900
	A	pplicable Motor Output (kW)	0.75	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30	37	45	55	75	90
		pplicable Motor Output (HP)	1	2	3	5	7.5	10	15	20	25	30	40	50	60	75	100	125
	Τ	Rated Output Capacity (kVA)	2.0	3.2	4.4	6.8	10	13	20	26	30	36	48	58	72	86	102	138
	LDU	Rated Output Current (A)	5	8	11	17	25	33	49	65	75	90	120	146	180	215	255	346
ng	RMA	Overload Capacity	Rated output current: 120% for 1 minute, 160% for 3 seconds.															
ati	No	Max. Output Frequency (Hz)								0.00-	~600.0	0Hz						
IT F		Carrier Frequency (kHz)		2	~15kl	Hz(8k	Hz)				2~10	kHz(6	6kHz)			2~9	kHz (4kHz)
Itp	7	Rated Output Capacity (kVA)	1.9	2.8	4.0	6.4	9.6	12	19	25	28	34	45	55	68	81	96	131
ō	DUT	Rated Output Current (A)	4.8	4.8 7.1 10 16 24 31 47 62 71 86 114 139 171 204 242 329														
	∑	Overload Capacity	Rated output current: 150% for 1 minute, 180% for 3 seconds.															
	HE/	Max. Output Frequency (Hz)								0.00-	~300.0	0Hz						
		Carrier Frequency (kHz)								2~6k	Hz (21	(Hz)						
ing	In	put Current (A) Normal Duty	6.4	12	16	20	28	36	52	72	83	99	124	143	171	206	245	331
Rat		put Current (A) Heavy Duty	6.1	11	15	18.5	26	34	50	68	78	95 5 0 ()	118	136	162	196	233	315
t	R	ated voitage/Frequency					3-pn	aseAu	200	170	00(-1	5%~+	10%)	, 50/6	UHZ			
du	E	equency Tolerance								170	~200\ 7~63U	7ac 7						
		rive Weight	2	6+ 0	ЗКа		5	1+ 1k	'n	47	x+ 1 5	Z Ka	38.5+	1 5Ka	64	8+1	5Ka	86 5 + 1 5Kc
	Ef	ficiency (%)	96	96	96	96	96.5	96.5	96.5	96.5	96.5	96.5	97	97	97	97	97	97
	С	ooling Method	Natural							Fa	ancoc	oling						
	В	raking Chopper	cooling	ooling Frame A. B. C: built-in Frame D and above: optional													otional	
	DC Choke			Frame A, B, C: optional Frame D and above: built-in													uilt-in	
	EMIFilter						Optior	nal exte	ernall	EMI fil	ter is a	vailab	le upo	n puro	chase			
	EMC-COP01			VFDXXXC23A: optional; VFDXXC23E: built-in														
46	0V	Frame Size				А						В				(С	
		Model VFDC	007	015	0:	22	037	040	0	55	075	11	0 1	150	185	22	0	300
	A	oplicable Motor Output (kW)	0.75	1.5	2	.2	3.7	4.0	5	5.5	7.5	11		15	18.5	23	2	30
	A	oplicable Motor Output (HP)	1	2	:	3	5	5	7	.5	10	15	5	20	25	3	D	40
	≻	Rated Output Capacity (kVA)	2.4	3.2	4	.8	7.2	8.4		10	14	19)	25	30	3	6	48
	DUT	Rated Output Current (A)	3.0	4.0	6	.0	9.0	10.5	5	12	18	24	Ļ	32	38	4	5	60
g	MAL	Overload Capacity					Ra	ited ou	tput c	urrent	: 120%	for 1	minute	e, 1609	% for 3	second	ds.	
atir	NOR	Max. Output Frequency (Hz)							0.0	0~60	0.00Hz	:						
t R		Carrier Frequency (kHz)					2~1	5kHz	(8kHz	<u>z</u>)					2~1	10kHz	:(6k⊦	łz)
tpu	≥	Rated Output Capacity (kVA)	2.3	3.0	4	.5	6.5	7.6	ę	9.6	14	18	3	24	29	34	4	45
0 n	5	Rated Output Current (A)	2.9	3.8	5	.7	8.1	9.5		11	17	23	3	30	36	43	3	57
	Å						ка	ited ou					minute	9, 1805	% TOF 3	second	JS.	
	뽀	Max. Output Frequency (Hz)							2~	0~300	J.UUHZ (クレロマ	<u>.</u>						
		Carrier Frequency (KHZ)	1 2	5.0	0	7	14	15 4	2~	0KHZ	20)	2	25	40	4	7	63
ting		put Current (A) Heavy Duty	4.5	5.6	8	. <i>1</i> 3	13	14	5	16	19	20	5	33	38	4	, 5	60
Rai	Ra	ated Voltage/Frequency		0.0	Ū	 3-p	bhase	AC 38	0V~4	-80V (-15%	~+10°	, %).50	/60H:	z			
out	0	perating Voltage Range							32	` 23~52	28Vac		,,					
<u> </u>	Fr	equency Tolerance								47~63	3Hz							
	Dı	ive Weight			2	.6± 0.	.3Kg					5.4±	1Kg			9.8±	1.5Kg	
	Ef	ficiency (%)	96	96	9	6	96	96	ę	96	96	96	9	6.5	96.5	96	.5	96.5
	Cooling Method		Natural	cooling	3						Fand	coolin	g					
	Braking Chopper		Frame A, B, C: built-in ; Frame D and above: optional															
	DC Choke		Frame A, B, C: optional ; Frame D and above: built-in															
	EI	MIFilter	Frame	A,B,C	VFD_	C4	Frame 3A: no VF	e A,B,C e EMI fi €DXXX	VFD Iter (C C43E:	XXXC)ptiona : built-ii	43E: b al exte n.	uilt-in rnal E	EMI fil MI filte	lter er is av	ailable	e upon	purch	nase),

NOTES:

•The carrier frequency is default. Increasing the carrier frequency requires a reduction in current, please refer to Pr. 06-55 Derating Protection drawing.

The motor drive should operate in derating current when its control method is set to FOC Sensorless, TQC+PG, TQC Sensorless, PM+PG and PM Sensorless modes.

When the application is performing impact load, select the motor drive with one grade larger capacity. •For FRAME A, B and C, Model VFD___C43A is under IP20/NEMA1/UL TYPE1 protection level. •For FRAME D and above, if the last character of the model is A then it is under IP20 protection level but the wiring terminal is under IP20 protection level; if the last character of the model is E, it is under IP20/NEMA1/UL TYPE1 protection level.

4	50	v	Frame Size	D0		D		E	Ξ		F	(3		ł	Н	
		Ϊ	Model VFDC	370	450	550	750	900	1100	1320	1600	1850	2200	2800	3150	3550	4500*
		Α	pplicable Motor Output (kW)	37	45	55	75	90	110	132	160	185	220	280	315	355	450
		Α	pplicable Motor Output (HP)	50	60	75	100	125	150	175	215	250	300	375	425	475	600
		~	Rated Output Capacity (kVA	58	73	88	120	143	175	207	247	295	367	438	491	544	720
		DUT	Rated Output Current (A)	73	91	110	150	180	220	260	310	370	460	550	616	683	866
	ת	NAL	Overload Capacity		Rated output current: 120% for 1 minute, 160% for 3 seconds.												
		lori	Max. Output Frequency (Hz)		0.00~600.00Hz												
ò	Carrier Frequency (kHz)				2~10kH	lz (6kH	z)				:	2~9kHz	(4kHz)			
		≻	Rated Output Capacity (kVA	55	69	84	114	136	167	197	235	280	348	417	466	517	677
		DUT	Rated Output Current (A)	69	86	105	143	171	209	247	295	352	437	523	585	649	816
	,	λ	Overload Capacity					Rate	d outpu	t currer	it: 150%	for 1 m	inute, 1	80% for	3 secono	ds.	
		HEA	Max. Output Frequency (Hz)		0.00~300.00Hz												
			Carrier Frequency (kHz)						:	2~6kHz	z(2kHz)					
	Input Current (A) Normal Duty			74	101	114	157	167	207	240	300	380	400	494	555	625	866
	Input Current (A) Heavy Duty				96	108	149	159	197	228	285	361	380	469	527	594	816
0		R	ated Voltage/Frequency		3-phaseAC 380V~480V(-15%~+10%),50/60Hz												
	2	0	perating Voltage Range		323~528Vac												
÷		F	requency Tolerance		47~63Hz												
		D	rive Weight		38.5	± 1.5Kg		64.8±	1.5Kg	86.5±	:1.5Kg	134 :	±4Kg		22	28	
		E	fficiency (%)	97	97	97	97	97	97	97	97	97.5	97.5	97.5	97.5	97.5	97.5
		С	ooling Method	_						Fanc	ooling						
		В	raking Chopper				Fra	me A, B	, C: buil	lt-in ; Fr	ame D a	nd abov	/e: optic	onal			
		D	C Choke	_			Fra	me A, B	, C: opt	ional ; F	rame D	and abo	ove: bui	lt-in			
		E	MIFilter				Opti	onal ex	ternal E	MI filter	is avail	able up	on purcl	hase			
		E	MC-COP01					VFDXX	XC43A:	optiona	al; VFDX	XC43E	: built-ir	ו			
6	e	ne	eral Specifications											* Availat	le in Chir	na and Ta	wan only.
	T	Co	ontrol Method	Pulse Wi	dth Mo	dulated	(PWM))									
		Co	ontrol Mode	1: V/F, 2: SVC, 3: VF+PG, 4: FOC+PG, 5: TQC+PG, 6: PM+PG, 7: FOC sensorless, 8: TQC sensorless, 9: PM sensorless													
		St	arting Torque	Reachup	o to 150	% or ab	ove at ().5Hz.U	Jnder F	OC+P	Gmode	, startii	ng torqi	uecanı	each 1	50% at	0Hz.

	Starting Torque	Reach up to 150% or above at 0.5Hz. Under FOC+PG mode, starting torque can reach 150% at 0Hz.
	V/f Curve	4-point adjustable V/f curve and square curve
	Speed Response Ability	5Hz (vector control can reach up to 40Hz)
	Torque Limit	Normal duty 160%, heavy duty 180% of torque current
	Torque Accuracy	±5%
	Max. Output Frequency (Hz)	Normal duty:0.00~600.00Hz; Heavy duty: 0.00 ~ 300.00 Hz
0	Frequency Output Accuracy	Digital command:±0.01%, -10°C ~+40°C, Analog command:±0.1%, 25±10°C
Ë	Output Frequency Resolution	Digital command: 0.01Hz , Analog command: 0.03 X max. output frequency/60 Hz (\pm 11 bit)
CIELIS	Overload Capacity	Normal duty: rated output current is 120% for 60seconds, 160% for 3 seconds. Heavy duty: rated output current is 150% for 60seconds, 180% for 3 seconds.
ara	Frequency Setting Signal	+10V~-10,0~+10V,4~20mA,0~20mA,Pulse input
ا د	Accel./decel. Time	0.00~600.00/0.0~6000.0 Seconds
Control	Main Control Function	Torque control, Droop control, Speed/torque control switching, Feed forward control, Zero-servo control, Momentary power loss ride thru, Speed search, Over-torque detection, Torque limit, 17-step speed (max), Accel/decel time switch, S-curve accel/decel, 3-wire sequence, Auto-Tuning (rotational, stationary), Dwell, Cooling fan on/off switch, Slip compensation, Torque compensation, JOG frequency, Frequency upper/lower limit settings, DC injection braking at start/stop, High slip braking, PID control (with sleep function), Energy saving control, MODOBUS communication (RS-485 RJ45, max. 115.2 kbps), Fault restart, Parameter copy
	Fan Control	230V model : VFD150C23A(include) and series above: PMW control; VFD110 C23A and series below: on/off switch control 460V model : VFD185 C43A(include) and series above: PMW control; VFD150C43A and series below: on/off switch control
	Motor Protection	Electronic thermal relay protection
LISUC	Over-current Protection	Over-current protection for 240% rated current current clamp『Normal duty: around 170~175%』;『Heavy duty: around180~185%』
aracte	Over-voltage Protection	230: drive will stop when DC-BUS voltage exceeds 410V 460: drive will stop when DC-BUS voltage exceeds 820V
Ë	Over-temperature Protection	Built-in temperature sensor
	Stall Prevention	Stall prevention during acceleration, deceleration and running independently.
DIECTIO	Restart after Instantaneous Power Failure	Parameter setting up to 20 seconds
2	Grounding Leakage Current Protection	Leakage current is higher than 50% of the AC motor drive's rated current
	Ceritifications	



Wiring

Wiring Diagram for Frame A~C



Note: It is not recommended to use a power capacitor or automatic power factor regulator (APFR) at the power input side. If the system requires such a device, please make sure a reactor is installed between the drive and the power capacitor or APFR.

Wiring Diagram for Frame D and Frames Above

*It provides 3-phase power





Dimensions

Digital Keypad





Frame B



D D1 0 Ē -5 C -С С ⊕ Ħ١



Detail A (Mounting Hole)



Detail B (Mounting Hole)

VFD055C23A VFD075C23A VFD110C23A VFD075C43A/43E VFD110C43A/43E VFD150C43A/43E

Unit : mm[inch]

Fra	ame	W	Н	D	W1	H1	D1*	S 1	Ø1	Ø2	Ø3
D4	mm	190.0	320.0	190.0	173.0	303.0	77.9	8.5	22.2	34.0	28.0
BI	inch	7.48	12.60	7.48	6.81	11.93	3.07	0.33	0.87	1.34	1.10

D1*: Flange mounting



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Dimensions

Frame C



Frame D



MODEL	
-------	--

FRAME_D1 VFD300C23A VFD370C23A VFD550C43A VFD750C43A

FRAME	_D0-1
VFD370	C43S
VFD450	C43S

VFD75	0C43A													Unit : I	mm[inch]
Fr	ame	W	Н	D	W1	H1	H2	H3	D1*	D2	S1	S 2	Ø1	Ø2	Ø3
D4	mm	330.0	-	275.0	285.0	550.0	525.0	492.0	107.2	16.0	11.0	18.0	-	-	-
ויט	inch	12.99	-	10.83	11.22	21.65	20.67	19.37	4.22	0.63	0.43	0.71	-	-	-
Fr	ame	W	Н	D	W1	H1	H2	H3	D1*	D2	S1	S2			
D0 4	mm	280.0	-	255.0	235.0	500.0	475.0	442.0	94.2	16.0	11.0	18.0			
D0-1	inch	11.02	-	10.04	9.25	19.69	18.70	17.40	3.71	0.63	0.43	0.71			



Dimensions





MODEL

FRAME_D2 VFD300C23E VFD370C23E VFD550C43E VFD750C43E FRAME_D0-2 VFD370C43U

VFD450C43U

VFD75	0C43E													Unit : I	mm[inch]
Fr	ame	W	Н	D	W1	H1	H2	H3	D1*	D2	S1	S2	Ø1	Ø2	Ø3
50	mm	330.0	688.3	275.0	285.0	550.0	525.0	492.0	107.2	16.0	11.0	18.0	76.2	34.0	22.0
D2	inch	12.99	27.10	10.83	11.22	21.65	20.67	19.37	4.22	0.63	0.43	0.71	3.00	1.34	0.87
Fr	ame	W	Н	D	W1	H1	H2	H3	D1*	D2	S1	S2	Ø1	Ø2	Ø3
D0 2	mm	280.0	614.4	255.0	235.0	500.0	475.0	442.0	94.2	16.0	11.0	18.0	62.7	34.0	22.0
D0-2	inch	11.02	21.19	10.04	9.25	19.69	18.70	17.40	3.71	0.63	0.43	0.71	2.47	1.34	0.87





Fr	ame	W	Н	D	W1	H1	H2	H3	D1*	D2	S1	S 2	S 3	Ø1	Ø2	Ø3
=4	mm	370.0	-	300.0	335.0	589	560.0	528.0	143.0	18.0	13.0	13.0	18.0	-	-	-
E1	inch	14.57	-	11.81	13.19	23.19	22.05	20.80	5.63	0.71	0.51	0.51	0.71	-	-	-



Dimensions

Frame E



MODEL FRAME_E2 VFD450C23E VFD550C23E VFD750C23E VFD900C43E VFD1100C43E

Fr	ame	W	Н	D	W1	H1	H2	H3	D1*	D2	S1	S 2	S 3	Ø1	Ø2	Ø3
F 0	mm	370.0	715.8	300.0	335.0	589	560.0	528.0	143.0	18.0	13.0	13.0	18.0	22.0	34.0	92.0
E2	inch	14.57	28.18	11.81	13.19	23.19	22.05	20.80	5.63	0.71	0.51	0.51	0.71	0.87	1.34	3.62

D1*: Flange mounting

Unit : mm[inch]





	NODI FRAME /FD90 /FD13 /FD16	EL 5_ F1 0C23A 20C43A 00C43A														Unit : I	mm[inch]
	Fra	ame	W	Н	D	W1	H1	H2	H3	D1*	D2	S1	S2	S 3	Ø1	Ø2	Ø3
ĺ	-4	mm	420.0	-	300.0	380.0	800.0	770.0	717.0	124.0	18.0	13.0	25.0	18.0	92.0	35.0	22.0
	F1	inch	16.54	-	11.81	14.96	31.50	30.32	28.23	4.88	0.71	0.51	0.98	0.71	3.62	1.38	0.87



Dimensions

Frame F



N F V V V V	IODE RAME (FD900 (FD132) (FD160	EL 5_F2 0C23E 20C43E 00C43E														Unit : r	nm[inch]
	Fra	ame	W	Н	D	W1	H1	H2	H3	D1*	D2	S1	S 2	S 3	Ø1	Ø2	Ø3
	50	mm	420.0	940.0	300.0	380.0	800.0	770.0	717.0	124.0	18.0	13.0	25.0	18.0	92.0	35.0	22.0
	F2	inch	16.54	37.00	11.81	14.96	31.50	30.32	28.23	4.88	0.71	0.51	0.98	0.71	3.62	1.38	0.87

Frame G



MOI FRAI VFD	DEL ME_G1 850C43A 2200C43A												Unit :	mm[inch]
	-rame	W	Н	D	W1	H1	H2	H3	S1	S2	S 3	Ø1	Ø2	Ø3
04	mm	500.0	-	397.0	440.0	1000.0	963.0	913.6	13.0	26.5	27.0	-	-	-
Gi	inch	19.69	-	15.63	217.32	39.37	37.91	35.97	0.51	1.04	1.06	-	-	-



Dimensions

Frame G



MOD FRAM VFD18 VFD22	EL E_G2 350C43E 200C43E												Unit :	mm[inch]
F	rame	W	Н	D	W1	H1	H2	H3	S 1	S 2	S 3	Ø1	Ø2	Ø3
00	mm	500.0	1240.2	397.0	440.0	1000.0	963.0	913.6	13.0	26.5	27.0	22.0	34.0	117.5
G2	inch	19.69	48.83	15.63	217.32	39.37	37.91	35.97	0.51	1.04	1.06	0.87	1.34	4.63

Frame H

MODEL

Frame

Frame

H1

H1



* Available in China and Taiwan only.



H4

Ø3

_

Dimensions

90

90

D5

MODEL

FRAME_H2 VFD2800C43E-1 VFD3150C43E-1 VFD3550C43E-1 VFD4500C43E-1*

Frame H



Fr	ame	W	Н	D	W1	W2	W3	W4	W5	W6	H1	H2	H3	H4
110	mm	700.0	1745.0	404.0	630.0	500.0	630.0	760.0	800.0	-	1729.0	1701.6	-	-
H2	inch	27.56	68.70	15.91	24.80	19.69	24.80	29.92	31.50	-	68.07	66.99	-	-
Fr	ame	H5	D1	D2	D3	D4	D5	D6	S1	S2	S 3	Ø1	Ø2	Ø3
ЦЭ	mm	-	51.0	38.0	65.0	204.0	68.0	137.0	13.0	26.5	25.0	-	-	-
Π2	inch	-	2.01	1.50	2.56	8.03	2.68	5.39	0.51	1.04	0.98	-	-	-

* Available in China and Taiwan only.



MODEL

FRAME_H3 VFD2800C43E VFD3150C43E VFD3550C43E

VFD4500C43E* Frame

H3

mm

W

700.0



нз	inch	27.56	68.70	15.91	24.80	19.69	24.80	29.92	31.50	-	68.07	66.99	-	-
Fra	ame	H5	D1	D2	D3	D4	D5	D6	S1	S 2	S 3	Ø1	Ø2	Ø3
112	mm	-	51.0	38.0	65.0	204.0	68.0	137.0	13.0	26.5	25.0	22.0	34.0	117.5
пэ	inch	-	2.01	1.50	2.56	8.03	2.68	5.39	0.51	1.04	0.98	0.87	1.34	4.63
_														

* Available in China and Taiwan only.



H4

Option Cards

EMC-PG01L

	Те	erminals	Descriptions
		VP	Output voltage for power: +5V/+12V±5% (use FSW3 to switch +5V/+12V) Max. output current: 200mA
Contraction of the	PG1	DCM	Common for power and signal
		A1, /A1 ,B1, /B1, Z1, /Z1	Encoder input signal (Line Driver) It can be 1-phase or 2-phase input; Max. input frequency: 300kP/sec
Set by	PG2	A2, /A2, B2, / B2	Pulse input signal (Line Driver or Open Collector) Open collector input: +5V/+12V (Note1) It can be 1-phase or 2-phase input; Max. input frequency: 300kP/sec.
Pr.10-00~10-02	PG OUT	AO, /AO, BO, /BO, ZO, /ZO , SG	PG card output signals. It has division frequency function: 1~255 times Max. output voltage for Line driver: 5Vdc Max. output current: 50mA; Max. output frequency: 300kP/sec SG: The GND of PG card is the same as the host controller or PLC, so a common output signal is attained.

EMC-PG010

	T	erminals	Descriptions
		VP	Output voltage for power: +5V/+12V±5% (use FSW3 to switch +5V/+12V) Max. output current: 200mA
	PG1	DCM	Common for power and signal
		A1, /A1 ,B1, /B1, Z1, /Z1	Encoder input signal (Line Driver or Open Collector) Open collector input: +5V/+12V (Note1) It can be 1-phase or 2-phase input; Max. input frequency: 300kP/sec
Sot by	PG2	A2, /A2, B2, / B2	Pulse input signal (Line Driver or Open Collector) Open collector input: +5V/+12V (Note1) It can be 1-phase or 2-phase input; Max. input frequency: 300kP/sec.
Set by Pr.10-00~10-02		V+ ,/V-	Needs external power source for PG OUT circuit. Input voltage of power:+12V ~ +24V
		V-	Negative power supply input
	PG OUT	A/O, B/O, ZO,	PG card output signals. It has division frequency function: 1~255 times Add a pull-up resistor to the open collector output signals to avoid signal interferences. [Three pull-up resistors are included in the package (1.8kΩ/1W)] Max. Output current: 20mA: Max output frequency: 300KP/Sec

EMC-PG01R

	Terminals		Descriptions
Set by Pr.10-00~10-02	PG1	R1- R2	Resolver output power 7Vrms, 10kHz
		S1,S2, S3, S4,	Resolver input signal 3.5±0.175Vrms, 10kHz
	PG2	A2, /A2, B2, / B2	Pulse input signal (Line Driver or Open Collector) Open collector input: +5V/+12V (Note1) It can be 1-phase or 2-phase input; Max. input frequency: 300kP/sec.
	PG OUT	AO, /AO, BO, /BO, ZO, /ZO , SG	PG card output signals. It has division frequency function: 1~255 times Max. output voltage for Line driver: 5Vdc Max. output current: 50mA Max. output frequency: 300kP/sec SG: The GND of PG card is the same as the host controller or PLC, so a common output signal is attained.

EMC-PG01U ■ FJMP1S: Standard UVW Output Encoder; D: Delta Encoder

	Terminals		Descriptions
		VP	Output voltage for power: +5V/+12V±5% (use FSW3 to switch +5V/+12V) Max. output current: 200mA
		DCM	Common for power and signal
Set by Pr.10-00~10-02	PG1	A1, /A1 ,B1, /B1, Z1, /Z1	Encoder input signal (Line Driver) 1-phase or 2-phase input. Max. input frequency: 300kP/sec
		U1, /U1, V1, /V1, W1, /W1	Encoder input signal
	PG2	A2, /A2, B2, / B2	Pulse input signal Open collector input: +5V/+12V (Note1) 1-phase or 2-phase input; Max. input frequency: 300kP/sec.
	PG OUT	AO, /AO, BO, /BO, ZO, /ZO, SG	PG card output signals. Division frequency function: 1~255 times Max. output voltage for Line driver: 5Vdc Max. output current: 50mA Max. output frequency: 300kP/sec SG: The GND of PG card is the same as the host controller or PLC, so a common output signal is attained.

Note 1: For the Open Collector, set input voltage to 5~15mA and install a pull-up resistor

[5V] Recommend pull-up resistor: $100 \sim 220\Omega$, 1/2W and above

[12V] Recommend pull-up resistor: 510~1.35k Ω , 1/2W and above

[24V] Recommend pull-up resistor: $1.8k{\sim}3.3k\Omega$, 1/2W and above

Screw Specifications for Option Card Terminals

EMC-D42A / EMC-D611A	Wire gauge	24~12AWG(0.205~3.31mm ²)
EMC-BPS01	Torque	4Kg-cm [3.47Ib-in]
	Wire gauge	24~16AWG (0.205~1.31mm ²)
	Torque	6Kg-cm [5.21lb-in]
EMC-PG01L / EMC-PG01O	Wire gauge	30~16AWG(0.0509~1.31mm ²)
EMC-PG01R / EMC-PG01U	Torque	2Kg-cm [1.74lb-in]





Option Cards

EMC-D42A

	Terminals	Descriptions
I/O Extension Card	СОМ	Common for multi-function input terminals Select SINK (NPN) / SOURCE (PNP) in J1 jumper / external power supply
	MI10~ MI13	Refer to parameters 02-26~02-29 to program the multi-function inputs MI10~MI13. Internal power is applied from terminal E24: +24Vdc±5% 200mA, 5W External power +24Vdc: max. voltage 30Vdc, min. voltage 19Vdc, 30W ON: the activation current is 6.5mA; OFF: leakage current tolerance is 10µA
	MO10~MO11	Multi-function output terminals (photocoupler) Duty-cycle: 50%; Max. output frequency: 100Hz Max. current: 50mA; Max. voltage: 48Vdc
	МХМ	Common for multi-function output terminals MO10, MO11(photocoupler) Max 48Vdc 50mA

EMC-D611A

I/O Extension Card	Terminals	Descriptions
	AC	AC power common for multi-function input terminal (Neutral)
	MI10~Mi15	Refer to Pr. 02.26~ Pr. 02.31 for multi-function input selection Input voltage: 100~130VAC; Input frequency: 57~63Hz Input impedance: 27Kohm Terminal response time: ON: 10ms; OFF: 20ms

EMC-R6AA

	Terminals	Descriptions
Relay Extension Card	RA10~RA15 RC10~RC15	Refer to Pr. 02.36~ Pr. 02.41 for multi-function input selection Resistive load: 3A(N.O.)/250VAC 5A(N.O.)/30Vdc Inductive load (COS 0.4) 2.0A(N.O.)/250VAC 2.0A(N.O.)/30Vdc It is used to output each monitor signal, such as for drive in operation, frequency attained or overload indication.

EMC-BPS01

	Terminals	Descriptions
Power Shift Card	24V GND	 When the AC motor drive power is off, the external power supply card provides external power to the network system, PLC function, and other functions to allow continued operations. Input power: 24V±5% Maximum input current: 0.5A Note: (1) Do not connect the control terminal +24V (Digital control signal common: SOURCE) directly to the EMC-BPS01 input terminal 24V. (2) Do not connect control terminal GND directly to the EMC-BPS01 input terminal GND.

CMC-MOD01



Features

- MDI/MDI-X auto-detect
- Virtual serial port.
- Supports MODBUS TCP protocol
- AC motor drive keypad/Ethernet configuration

Network Interface

Interface Number of ports Transmission method IEEE 802.3, IEEE 802.3u Transmission cable

RJ-45 with Auto MDI/MDIX 1 Port Category 5e shielding 100M Transmission speed Network protocol

E-mail alarm

■ Baud rate: 10/100Mbps auto-detect

10/100 Mbps Auto-Detect ICMP, IP, TCP, UDP, DHCP, SMTP, MODBUS OVER TCP/IP, **Delta Configuration**

CMC-EIP01

Features



■ MDI/MDI-X auto-detect

- uto-detect
 Virtual serial port
- Supports MODBUS TCP and Ethernet/IP protocol
- Baud rate: 10/100Mbps auto-detect
- AC motor drive keypad/Ethernet configuration

Network Interface

Interface
Number of ports
Transmission method
Transmission cable

RJ-45 with Auto MDI/MDIX 1 Port IEEE 802.3, IEEE 802.3u Category 5e shielding 100M Transmission speed Network protocol 10/100 Mbps Auto-Detect ICMP, IP, TCP, UDP, DHCP, SMTP, MODBUS OVER TCP/IP, Delta Configuration

CMC-PD01



Features

- Supports PZD control data exchange
- Supports PKW polling AC motor drive parameters
- Supports user diagnosis function
- Auto-detects baud rates; supports Max. 12Mbps

M G C

S s

PROFIBUS DP Connector

Interface
Transmission method
Transmission cable
Electrical isolation

DB9 connector High-speed RS-485 Shielded twisted pair cable 500VDC

Communication

essage type	Cyclic data exchange
odule name	CMC-PD01
SD document	DELA08DB.GSD
ompany ID	08DB (HEX)
erial transmission beed supported luto-detection)	9.6kbps; 19.2kbps; 93.75kbps; 187.5kbps; 125kbps; 250kbps; 500kbps; 1.5Mbps; 3Mbps; 6Mbps; 12Mbps (bits per second)

CMC-DN01



Features

- Based on the high-speed communication interface of Delta HSSP protocol, able to conduct immediate control of AC motor drive.
- Supports Group 2 only connection and polling I/O data exchange.
- For I/O mapping, supports Max. 32 words of input and 32 words of output.
- Supports EDS file configuration in DeviceNet configuration software.
- Supports all baud rates on DeviceNet bus: 125kbps, 250kbps, 500kbps and extendable serial transmission speed mode.
- Node address and serial transmission speed can be set up on AC motor drive.
- Power supplied from AC motor drive.

DeviceNet Connector

Interface	5-PIN open removable connector. Of 5.08mm PIN interval	Inte Tra
Transmission method	CAN	_
Transmission cable	Shielded twisted pair cable (with 2 power cables)	Cor
Transmission speed	125kbps, 250kbps, 500kbps and extendable serial transmission speed mode	
Network protocol	DeviceNet protocol	

AC Motor Drive Connection Port

Interface	50 PIN communication terminal
Transmission method	SPI communication
Terminal function	1. Communicating with AC motor drive 2. Transmitting power supply from AC motor drive
Communication protocol	Delta HSSP protocol



Option Cards

EMC-COP01

Built-in EMC-COP01 card are available for VFD___C23E and VFD___C43E.



RJ-45 Pin definition							
		Pin	F				
0000000		1	C				
		2	C				
⊆-/////// 8~1	8~1	3	C				
Mala	Eamolo	6	C				
wate	remaie						

Pin name Definition CAN_H CAN_H bus line (dominant high) CAN_L CAN_L bus line (dominant low) CAN_GND Ground/0V/V CAN_GND Ground/0V/V

Network Interface

Interface	RJ-45
Number of ports	1 Port
Transmission method	CAN
Transmission cable	CAN standard cable
Transmission speed	1M 500k 250k 125k 100k 50k
Communication protocol	CANopen

CANopen Communication Cable Model: TAP-CB05, TAP-CB10



Digital Keypad Accessories: RJ45 Extension Leads and CMC-EIP01 Cables Applicable Models: CBC-K3FT \ CBC-K5FT \ CBC-K7FT \ CBC-K10F \ CBC-K16FT

Title	Part No.	Explanation
1	CBC-K3FT	RJ45 extension lead, 3 feet (approximately 0.9m)
2	CBC-K5FT	RJ45 extension lead, 5 feet (approximately 1.5m)
3	CBC-K7FT	RJ45 extension lead, 7 feet (approximately 2.1m)
4	CBC-K10FT	RJ45 extension lead, 10 feet (approximately 3m)
5	CBC-K16FT	RJ45 extension lead, 16 feet (approximately 4.9m)

Model Name



Series name (Variable Frequency Drive)

Ordering information

Frame Size	Power Range		Мс	odels	
Frame A	230V: ND: 0.75~3.7kW HD: 0.4~2.2kW 460V: ND: 0.75~5.5kW HD: 0.4~4.0kW	VFD007C23A VFD015C23A VFD022C23A VFD037C23A	VFD007C43A VFD015C43A VFD022C43A VFD037C43A VFD040C43A VFD055C43A	VFD007C43E VFD015C43E VFD022C43E VFD037C43E VFD040C43E VFD055C43E	
Frame B	230V: ND: 5.5~11kW HD: 3.7~7.5kW 460V: ND: 7.5~15kW HD: 5.5~11kW	VFD055C23A VFD075C23A VFD110C23A	VFD015C43A VFD110C43A VFD110C43A	VFD075C43E VFD110C43E VFD150C43E	
Frame C	230V: ND: 15~22kW HD: 11~18.5kW 460V: ND: 18.5~30kW HD: 15~22kW	VFD150C23A VFD185C23A VFD220C23A	VFD185C43A VFD220C43A VFD300C43A	VFD185C43E VFD220C43E VFD300C43E	
Frame D	230V: ND: 30~37kW HD: 20~30kW 460V: ND: 37~75kW HD: 30~45kW	Frame_D1 VFD300C23A VFD370C23A VFD550C43A VFD750C43A	Frame_D0-1 VFD370C43S VFD450C43S	Frame_D2 VFD300C23E VFD370C23E VFD550C43E VFD750C43E	Frame_D0-2 VFD370C43U VFD450C43U
Frame E	230V: ND: 45~75kW HD: 37~55kW 460V: ND: 90~110kW HD: 55~90kW	Frame_E1 VFD450C23A VFD550C23A VFD750C23A VFD900C43A VFD1100C43A	Frame_E2 VFD450C23E VFD550C23E VFD750C23E VFD900C43E VFD1100C43E		
Frame F	230V: ND: 90kW HD: 75kW 460V: ND: 132~160kW HD: 110~132kW	Frame_F1 VFD900C23A VFD1320C43A VFD1600C43A	Frame_F2 VFD900C23E VFD1320C43E VFD1600C43E		
Frame G	460V: ND: 185~220kW HD: 160~185kW	Frame_G1 VFD1850C43A VFD2200C43A	Frame_G2 VFD1850C43E VFD2200C43E		
Frame H	460V: ND: 280~450kW HD: 220~355kW	Frame_H1 VFD2800C43A VFD3150C43A VFD3550C43A VFD4500C43A*	Frame_H2 VFD2800C43E-1 VFD3150C43E-1 VFD3550C43E-1 VFD4500C43E-1*	Frame_H3 VFD2800C43E VFD3150C43E VFD3550C43E VFD4500C43E*	

* Available in China and Taiwan only.



Standard Motors

Used with 400V Standard Motors It is recommended to add an AC output reactor when using with a 400V standard motor to prevent damage to motor insulation

Torque Characteristics and

Temperature Rise When a standard motor is drive controlled, the motor temperature will be higher than with DOL operation

Please reduce the motor output torque when operating at low speeds to compensate for less cooling efficiency.

For continuous constant torque at low speeds, external forced motor cooling is recommended.

Vibration

When the motor drives the machine resonances may occur, including machine resonances. Abnormal vibration may occur when operating a 2-pole motor at 60Hz or higher.

Noise

When a standard motor is drive controlled, the motor noise will be higher than with DOL operation.

To lower the noise, please increase the carrier frequency of the drive. The motor fan can be very noisy when the motor speed exceeds 60Hz.

Special Motors

High-speed Motor

To ensure safety, please try the frequency setting with another motor before operating the high-speed motor at 120Hz or higher.

Explosion-proof Motor

Please use a motor and drive that comply with explosion-proof requirements.

Submersible Motor & Pump

The rated current is higher than that of a standard motor

Please check before operation and select the capacity of the AC motor drive carefully. The motor temperature characteristics differ from a standard motor, please set the motor thermal time constant to a lower value.

Brake Motor

When the motor is equipped with a mechanical brake, the brake should be powered by the mains supply.

Damage may occur when the brake is powered by the drive output. Please DO NOT drive the motor with the brake engaged.

Gear Motor

In gearboxes or reduction gears, lubrication may be reduced if the motor is continuously operated at low speeds Please DO NOT operate in this way

Synchronous Motor

These motors need suitable software for control. Please contact Delta for more information

Single-phase Motor

Single-phase motors are not suitable for being operated by an AC Motor Drive. Please use a 3-phase motor instead when necessary.

Attention

Environmental Conditions

Installation Position

- 1. The drive is suitable for installation in a place with ambient temperature from -10 to 50^[J] 2. The surface temperature of the drive and brake resistor will rise under specific
- operation conditions. Therefore, please install the drive on materials that are noncombustible.
- Ensure that the installation site complies with the ambient conditions as stated in the manual.

Wiring

Limit of Wiring Distance For the remote operation, please use twist-shielding cable and the distance between the drive and control box should be less than

Maximum Motor Cable Length Motor cables that are too long may cause overheating of the drive or current peaks due to

strav capačitance Please ensure that the motor cable is less than

If the cable length can't be reduced, please lower the carrier frequency or use an AC reactor.

Choose the Right Cable Please refer to current value to choose the right cable section with enough capacity or use recommended cables.

Grounding Please ground the drive completely by using the grounding terminal.

How to Choose the Drive Capacity

Standard Motor

Please select the drive according to applicable motor rated current listed in the drive specification.

Please select the next higher power AC drive in case higher starting torgue or guick acceleration/deceleration is needed.

Special Motor

Please select the drive according to: Rated current of the drive > rated current of the motor

Transportation and Storage

Please transport and store the drive in a place that meets environment specifications.

Peripheral Equipment

Molded-Case Circuit Breakers

(MCCB) Please install the recommended MCCB or ELCB in the main circuit of the drive and make sure that the capacity of the breaker is equal to or lower than the recommended one.

Add a Magnetic Contactor(MC) in

the Output Circuit When a MC is installed in the output circuit of the drive to switch the motor to commercial power or other purposes, please make sure that the drive and motor are completely stopped and remove the surge absorbers from the MC before switching it.

Add a Magnetic Contactor (MC) in the Input Circuit Please only switch the MC ONCE per hour or it may damage the drive. Please use RUN/STOP signal to switch many times during motor operation.

Motor Protection The thermal protection function of the drive can be used to protect the motor by setting the operation level and motor type (standard motor or variable motor). When using a high-speed motor or a water-cooled motor the thermal time constant should be set to a lower value.

When using a longer cable to connect the motor thermal relay to a motor, high-frequency currents may enter via the stray capacitance. It may result in malfunctioning of the relay as the real current is lower than the setting of thermal relay. Under this condition, please lower the carrier frequency or add an AC reactor to solve this.

DO NOT Use Capacitors to Improve the Power Factor

Use a DC reactor to improve the power factor of the drive. Please DO NOT install power factor correction capacitors on the main circuit of the drive to prevent motor faults due to over current.

Do NOT Use Surge Absorber Please DO NOT install surge absorbers on the output circuit of the drive.

Lower the Noise

To ensure compliance with EMC regulations, usually a filter and shielded wiring is used to lower the noise.

Method Used to Reduce the Surge Current

Surge currents may occur in the phase-lead capacitor of the power system, causing an overvoltage when the drive is stopped or at low loads.

It is recommended to add a DC reactor to the drive.

Leading the Future of Drive Technology

Delta has reviewed the contents of this catalogue to ensure its consistency with the manual. However, due to product updates we can not guarantee there are no inconsistencies. We reserve the right to change or update the content without prior notice. All names, icons, photos, and trademarks are Delta's sole property. No part of this catalogue shall be copied, reproduced, or transmitted without prior written authorization from Delta Electronics, Inc.





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