

Automation for a Changing World

## Delta Vector Control Drive C2000 Series



Smarter. Greener. Together.

## powerful Featuress rligh Fiffclene

The C2000 series AC motor drive provides the most efficient and cost-effective solution for all types of drive applications. It features precise speed, torque and position control functions that are suitable for both sensor and sensorless types of synchronous and asynchronous motors. The C2000 series is also equipped with built-in PLC functions and supports the CANopen Master/Slave extension for the ultimate in system flexibility and fast data exchange.

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## Standard Models (IP20/NEMA1)

Power range: 230V 0.75~90kW, 460V 0.75~450kW

| 230 V (kW) | 0.75 | 1.5 | 2.2 | 3.7 | 5.5 | 7.5 | 11 | 15 | 18.5 | 22 | 30 | 37 | 45 | 55 | 75 | 90 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 230 V (HP) | 1 | 2 | 3 | 5 | 7.5 | 10 | 15 | 20 | 25 | 30 | 40 | 50 | 60 | 75 | 100 | 125 |
| Frame Size | A |  |  |  | B |  |  | C |  |  | D |  | E |  |  | F |
| Braking Chopper | Built-in |  |  |  |  |  |  |  |  |  | Optional |  |  |  |  |  |
| DC Reactor | Optional |  |  |  |  |  |  |  |  |  | Built-in |  |  |  |  |  |
| EMI Filter | Optional |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| Protection Level | IP20 |  |  |  |  |  |  |  |  |  | IP00 / IP20 |  |  |  |  |  |


| 460 V (kW) | 0.75 | 1.5 | 2.2 | 3.7 | 4.0 | 5.5 | 7.5 | 11 | 15 | 18.5 | 22 | 30 | 37 | 45 | 55 | 75 | 90 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 460 V (HP) | 1 | 2 | 3 | 5 | 5 | 7.5 | 10 | 15 | 20 | 25 | 30 | 40 | 50 | 60 | 75 | 100 | 125 |
| Frame Size | A |  |  |  |  |  |  | B |  |  | C |  | D0 |  | D |  | E |
| Braking Chopper | Built-in |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| DC Reactor | Optional |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| EMI Filter | Built-in (VFD___C43E) |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| Protection Level | IP20 |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |

*Available in China and Taiwan only.

## Advanced Drive Controls

## - Door Width Auto-tuning

1. High bandwidth control
2. Speed/torque/position control mode
3. Dual rating design
(Normal duty/heavy duty)
4. 4-quadrant torque control and limit
5. For both synchronous and asynchronous motors

## - Environmental Adaptability

1. $50^{\circ} \mathrm{C}$ operating temperature
2. Built-in DC reactor
3. Coated circuit boards
4. Built-in EMI filter
5. Global safety standards (CE/UL/cUL)

[^0]| 110 | 132 | 160 | 185 | 220 | 280 | 315 | 355 | 450* |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 150 | 175 | 215 | 250 | 300 | 375 | 425 | 475 | 600 |
|  | F |  | G |  | H |  |  |  |
| Optional |  |  |  |  |  |  |  |  |
| Built-in |  |  |  |  |  |  |  |  |
| Optional |  |  |  |  |  |  |  |  |
| IP00 / IP20 |  |  |  |  |  |  |  |  |

## - Versatile Drive Controls

1. Built-in safe stop function
2. Built-in PLC function
3. Built-in brake unit
4. Supports various network protocols
5. Synchronous point-to-point control

## - Modular Design

1. Hot plug LCD keypad
2. I/O extension cards
3. Various PG (encoder) feedback cards
4. Network cards for fieldbus modules
5. Removable fan


## Modular Design

■ Various accessories options, such as I/O extension cards, encoder feedback cards, communication cards, hot plug LCD keypad, removable terminals and removable fans.


- The modular design fulfills the needs of system applications and equipment maintenance.
- KPC-CC01 keypad

■ Standard RJ45 network cable.

- Easy to remove with one press

- The product nameplate shows the input/output voltage, input/output current, the frequency range, and more.

- RFI Switch


Modular fan design is easy to clean and replace providing longer service life.


## Excellent Environment Adaptability

- Built-in DC choke to surpress harmonics*
- Built-in EMI filter to filter noise*
- Conformal coating (Class 3C2 of IEC60721-3-3 standard) ensures drive operation stability and safety in critical environments.
- The electronic components of the drive are isolated from the cooling system to reduce heat interference. Dissipated heat can be discharged by flange-mounting installation, and forced fan cooling can import cold air into the heat sink. The heat dissipation performance is optimized by these two cooling methods.
*Note: Please refer to the Product Specification



## Certifications

UL, cUL
C-Tick

CE
C-Tick
ROHS
Low Voltage: EN61800-5-1
EMC: EN61000-3-12, EN61800-3, IEC61000-6-2, IEC61000-6-4, IEC61000-4-2,
IEC61000-4-3, IEC61000-4-4, IEC61000-4-5, IEC61000-4-6, IEC61000-4-8,

## Quick and easy parameters setting via the

 LCD keypad- Multi-column display for the drive status
- Simple and intuitive operation
- User-defined parameter groups
- Real Time Clock and calendar function
- Language selection for display
- Copy function saves parameters and PLC programs to the keypad memory for later transfer to another drive
- IP66 protection level



Create homepage logo


Editable message display


Editable chart display

## Intelligent PLC Functions

- Built-in 10K steps capacity of PLC functions. Distributed control and independent operation are easily achieved via network connection.
- CANopen Master protocol and PLC functions provide synchronous control and fast data exchange.



## High-speed Network

- Provides optional MODBUS RTU and various fieldbus cards for flexible communication applications
- Advanced network functions
- Built-in MODBUS communication interface
- CANopen (DS402)
- 



CB (B) S

Ability to control up to 8 Slave drives via the CANopen Master function

- Supports all Delta industrial automation products
(all EDS files of Delta industrial automation products are built-in) • TAP-CN03 distribution
- I/O data layout of each piece of equipment on the CANopen Network
- Planning function for motion control - WPL Soft


RJ45 cable



Delta DeviceNet Builder software is specially designed for DeviceNet communication. With this software, it is easy to plan DeviceNet equipment and remote I/O via parameters to build a standard DeviceNet monitoring structure.

Supports all Delta industrial automation products (all EDS files of Delta industrial automation products are built-in) I/O data layout of each piece of equipment in the DeviceNet network DeviceNet layout software


## - EtherNet/IPs

 - MODBUS TCPDelta's communication integrator software not only provides graphic module setting and a human interface design but also supports settings and online monitoring for all Ethernet products.

- Delta software for Ethernet/MODBUS TCP products Graphic module setting and human interface design Auto search function Setting interface for virtual COM port



## Convenient Operation Platform for Drive System Management

- Provides a complete operation platform for users' easy control and monitoring via PC, including parameters save/setting, real-time wave monitor, quick setup, for multiple languages and with multi-language operation systems.



## High-performance Field Oriented Control

- The FOC+PG mode of C2000 series can output $150 \%$ of starting torque at extremely low speeds for precise and stable speed control.



## Fast Response to Impact Load

During load changes, the VFD-C2000 calculates the required torque response and minimizes the vibration caused by load impact using FOC.


- Precise position and speed control ideal for printing machine applications.



## Auto Energy-Saving Operation

During constant speed operation, this function auto-calculates the best voltage value by the load power for the load.


## Deceleration Energy Backup (dEB)

This function controls the motor deceleration for stopping when an unexpected power shut down occurs to prevent mechanical damage. When power resumes, the motor will return to its previous speed.
— Input Voltage
— Motor Speed


```
- Input Voltage
_ Motor Speed
```



## A Drive for Permanent Magnet (PM) Motors

The C2000 is a dual mode drive to control both an induction motor and permanent magnet motor. The dynamic response of a PM motor provides precise control of position, speed and torque.


## Delta REG2000 Series for

 Power RegenerationUsing the REG2000 with the C2000 in a crane and hoist application provides the user with a four-quadrant operation and energy saving results.


## Delta AFE2000 Series for Power Regeneration and Power Quality Improvement

The Active Front End Unit (AFE2000) helps to reduce torque ripple and harmonics with a higher power factor to provide excellent production quality and outstanding energy saving results.


## Delta Active Front End AFE2000 Series

## Features

- Replaces traditional brake resistor to reduce heat generation.
- Clear energy savings: more than $95 \%$ of the regenerative energy is converted into electricity and supplied back to the mains.
- Full-load operation: input-side current THD lower than 5\% and improves power factor up to $99 \%$.
- AC motor drives with AFE2000: supports 4-quadrant operation with variable frequencies and adjustable system.
- Constant DC bus voltage: unaffected by mains voltage fluctuations.


Improves power factor and decreases harmonic distortion.
THD<=5\%, power factor > 99\%


Improves power factor by 20\%

## Applications

- Large-inertia loads, such as centrifuge equipment, dewatering machines and roving machines
- 4-quadrant loads including elevators, cranes and pumpjacks (oil extraction machines)
- Quick braking, such as machine tools, bag making machines, auto storage and retrieval systems, and lathes
- Long-term energy feedback, such as wind power, water power, steel printing and paper making machinery (winding equipment)
- Improves power quality for industries such as semiconductor and panel industries



## Operating Environment

DO NOT expose the AC motor drive to harsh environments, such as dust, direct sunlight, corrosive/ inflammable gasses, humidity, liquid or vibrations. The salt in the air must be less than $0.01 \mathrm{mg} / \mathrm{cm}^{2}$ per year.

| Installation location | IEC60364-1/IEC60664-1 Pollution degree 2, Indoor use only |  |
| :---: | :---: | :---: |
| Surrounding | Storage/ Transportation | $-25^{\circ} \mathrm{C} \sim+70^{\circ} \mathrm{C}$ |
| Temperature | No condensation, no frost |  |
| Rated Humidity | Operation | Max. 95\% |
|  | Storage/ Transportation | Max. 95\% |
|  | No condensation, no frost |  |
| Air Pressure | Operation/ Storage | 86 to 106 kPa |
|  | Transportation | 70 to 106 kPa |
| Pollution Level | IEC60721-3-3 |  |
|  | Operation | Class 3C2; Class 3S2 |
|  | Storage | Class 2C2; Class 2S2 |
|  | Transportation | Class 1C2; Class 1 S 2 |
|  | No condensation, no frost |  |
| Altitude | If AC motor drive is in If it is install at altitud temeperature for eve Grounded is 2000 m . | alled at altitude $0 \sim 1000 \mathrm{~m}$, follow normal operation restriction. $1000 \sim 3000 \mathrm{~m}$, decrease $2 \%$ of rated current or lower $0.5^{\circ} \mathrm{C}$ of 100 m increase in altitude. Maximum altitude for Corner |
| Package Drop | Storage/ Transportation | ISTA procedure 1A(according to weight) IEC60068-2-31 |
| Vibration | 1.0 mm , peak to peak value range from 2 Hz to $13.2 \mathrm{~Hz} ; 0.7 \mathrm{G} \sim 1.0 \mathrm{G}$ range from 13.2 Hz to 55 Hz ; <br> 1.0 G range from 55 Hz to 512 Hz . Comply with IEC 60068-2-6 |  |
| Impact | IEC/EN 60068-2-27 |  |
| Operation Position | Max. allowed offset angle $\pm 10^{\circ}$ (under normal installation position) |  |

## Specification for Operation Temperature and Protection Level

| Model | Frame | Top Cover | Conduit Box | Protection Level | Operation Temperature |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | $\begin{aligned} & \text { Frame A~C } \\ & \text { 230V: 0.75~22kW } \\ & \text { 460V: 0.75~30kW } \end{aligned}$ | Remove top cover | Standard conduit plate | IP20/UL Open Type | $-10^{\circ} \mathrm{C} \sim 50^{\circ} \mathrm{C}$ |
|  |  | Standard with top cover |  | IP20/UL Type1/NEMA1 | $-10^{\circ} \mathrm{C} \sim 40^{\circ} \mathrm{C}$ |
|  | $\begin{aligned} & \text { Frame D~H } \\ & 230 \mathrm{~V}:>22 \mathrm{~kW} \\ & 460 \mathrm{~V}:>30 \mathrm{~kW} \end{aligned}$ | N/A | No conduit box | $\begin{aligned} & \text { IP00 } \\ & \text { IP20/UL Open Type } \end{aligned}$ |  |
| VFDxxxCxxA VFDxxxCxxS |  |  |  |  | $-10^{\circ} \mathrm{C} \sim 50^{\circ} \mathrm{C}$ |
|  |  |  |  | IP00: for the circled area <br> IP20: for all other area |  |
| VFDxxxCxxE <br> VFDxxxCxxU | $\begin{aligned} & \text { Frame A~C } \\ & 460 \mathrm{~V}: 0.75 \sim 30 \mathrm{~kW} \end{aligned}$ | Remove top cover | Standard conduit plate | IP20/UL Open Type | $-10^{\circ} \mathrm{C} \sim 50^{\circ} \mathrm{C}$ |
|  |  | Standard with top cover |  | IP20/UL Type1/NEMA1 | $-10^{\circ} \mathrm{C} \sim 40^{\circ} \mathrm{C}$ |
|  | $\begin{aligned} & \text { Frame D~H } \\ & 230 \mathrm{~V}:>22 \mathrm{~kW} \\ & 460 \mathrm{~V}:>30 \mathrm{~kW} \end{aligned}$ | N/A | Standard conduit box | IP20/UL Type1/NEMA1 | $-10^{\circ} \mathrm{C} \sim 40^{\circ} \mathrm{C}$ |

## Specifications




| A |  |  |  |  |  | B |  |  | C |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 007 | 015 | 022 | 037 | 040 | 055 | 075 | 110 | 150 | 185 | 220 | 300 |
| 0.75 | 1.5 | 2.2 | 3.7 | 4.0 | 5.5 | 7.5 | 11 | 15 | 18.5 | 22 | 30 |
| 1 | 2 | 3 | 5 | 5 | 7.5 | 10 | 15 | 20 | 25 | 30 | 40 |
| 2.4 | 3.2 | 4.8 | 7.2 | 8.4 | 10 | 14 | 19 | 25 | 30 | 36 | 48 |
| 3.0 | 4.0 | 6.0 | 9.0 | 10.5 | 12 | 18 | 24 | 32 | 38 | 45 | 60 |
| Rated output current: $120 \%$ for 1 minute, 160\% for 3 seconds. |  |  |  |  |  |  |  |  |  |  |  |
| $0.00 \sim 600.00 \mathrm{~Hz}$ |  |  |  |  |  |  |  |  |  |  |  |
| $2 \sim 15 \mathrm{kHz}(8 \mathrm{kHz})$ |  |  |  |  |  |  |  |  | $2 \sim 10 \mathrm{kHz}(6 \mathrm{kHz})$ |  |  |
| 2.3 | 3.0 | 4.5 | 6.5 | 7.6 | 9.6 | 14 | 18 | 24 | 29 | 34 | 45 |
| 2.9 | 3.8 | 5.7 | 8.1 | 9.5 | 11 | 17 | 23 | 30 | 36 | 43 | 57 |
| Rated output current: $150 \%$ for 1 minute, 180\% for 3 seconds. |  |  |  |  |  |  |  |  |  |  |  |
| $0.00 \sim 300.00 \mathrm{~Hz}$ |  |  |  |  |  |  |  |  |  |  |  |
| $2 \sim 6 \mathrm{kHz}(2 \mathrm{kHz})$ |  |  |  |  |  |  |  |  |  |  |  |
| 4.3 | 5.9 | 8.7 | 14 | 15.5 | 17 | 20 | 26 | 35 | 40 | 47 | 63 |
| 4.1 | 5.6 | 8.3 | 13 | 14.5 | 16 | 19 | 25 | 33 | 38 | 45 | 60 |
| $3-\mathrm{phase} \mathrm{AC} 380 \mathrm{~V} \sim 480 \mathrm{~V}(-15 \% \sim+10 \%), 50 / 60 \mathrm{~Hz}$ |  |  |  |  |  |  |  |  |  |  |  |
| $323 \sim 528 \mathrm{Vac}$ |  |  |  |  |  |  |  |  |  |  |  |
| $47 \sim 63 \mathrm{~Hz}$ |  |  |  |  |  |  |  |  |  |  |  |
| $2.6 \pm 0.3 \mathrm{Kg}$ |  |  |  |  |  | $5.4 \pm 1 \mathrm{Kg}$ |  |  | $9.8 \pm 1.5 \mathrm{Kg}$ |  |  |
| 96 | 96 | 96 | 96 | 96 | 96 | 96 | 96 | 96.5 | 96.5 | 96.5 | 96.5 |
| Natural cooling |  |  |  |  |  | Fan cooling |  |  |  |  |  |
| Frame A, B, C: built-in ; Frame D and above: optional |  |  |  |  |  |  |  |  |  |  |  |
| Frame A, B, C: optional ; Frame D and above: built-in |  |  |  |  |  |  |  |  |  |  |  |
| Frame $A, B, C$ VFD___C43A: no EMI filter (Optional external EMI filter is available upon purchase) VFDXXX C43E: built-in. |  |  |  |  |  |  |  |  |  |  |  |

NOTES:
-The carrier frequency is default. Increasing the carrier frequency requires a reduction in current, please refer to Pr. 06-55 Derating Protection drawing.
-The motor drive should operate in derating current when its control method is set to FOC Sensorless,TQC+PG, TQC Sensorless, PM+PG and PM Sensorless modes.
When the application is performing impact load, select the motor drive with one grade larger capacity.
-For FRAME A, B and C, Model VFD___C43A is under IP20/NEMA1/UL TYPE1 protection level.
-For FRAME D and above, if the last character of the model is A then it is under IP20 protection level but the wiring terminal is under IP00 protection level;
if the last character of the model is E , it is under IP20/NEMA1/UL TYPE1 protection level.

|  | Frame Size |  | D0 | D |  |  | E |  | F |  | G |  | H |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Model VFD＿＿C | 370 | 450 | 550 | 750 | 900 | 1100 | 1320 | 1600 | 1850 | 2200 | 2800 | 3150 | 3550 | 4500＊ |
| Applicable Motor Output（kW） |  |  | 37 | 45 | 55 | 75 | 90 | 110 | 132 | 160 | 185 | 220 | 280 | 315 | 355 | 450 |
| Applicable Motor Output（HP） |  |  | 50 | 60 | 75 | 100 | 125 | 150 | 175 | 215 | 250 | 300 | 375 | 425 | 475 | 600 |
|  |  | Rated Output Capacity（kVA） | 58 | 73 | 88 | 120 | 143 | 175 | 207 | 247 | 295 | 367 | 438 | 491 | 544 | 720 |
|  |  | Rated Output Current（A） | 73 | 91 | 110 | 150 | 180 | 220 | 260 | 310 | 370 | 460 | 550 | 616 | 683 | 866 |
|  |  | Overload Capacity | Rated output current： $120 \%$ for 1 minute，160\％for 3 seconds． |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  |  | Max．Output Frequency（Hz） | $0.00 \sim 600.00 \mathrm{~Hz}$ |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  |  | Carrier Frequency（kHz） | $2 \sim 10 \mathrm{kHz}(6 \mathrm{kHz})$ |  |  |  | $2 \sim 9 \mathrm{kHz}(4 \mathrm{kHz})$ |  |  |  |  |  |  |  |  |  |
|  |  | Rated Output Capacity（kVA） | 55 | 69 | 84 | 114 | 136 | 167 | 197 | 235 | 280 | 348 | 417 | 466 | 517 | 677 |
|  |  | Rated Output Current（A） | 69 | 86 | 105 | 143 | 171 | 209 | 247 | 295 | 352 | 437 | 523 | 585 | 649 | 816 |
|  |  | Overload Capacity | Rated output current： $150 \%$ for 1 minute，180\％for 3 seconds． |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  |  | Max．Output Frequency（Hz） | $0.00 \sim 300.00 \mathrm{~Hz}$ |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  |  | Carrier Frequency（kHz） | $2 \sim 6 \mathrm{kHz}(2 \mathrm{kHz})$ |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  |  | put Current（A）Normal Duty | 74 | 101 | 114 | 157 | 167 | 207 | 240 | 300 | 380 | 400 | 494 | 555 | 625 | 866 |
|  |  | put Current（A）Heavy Duty | 70 | 96 | 108 | 149 | 159 | 197 | 228 | 285 | 361 | 380 | 469 | 527 | 594 | 816 |
|  |  | ated Voltage／Frequency | $3-$ phase AC $380 \mathrm{~V} \sim 480 \mathrm{~V}(-15 \% \sim+10 \%), 50 / 60 \mathrm{~Hz}$ |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  |  | perating Voltage Range | $323 \sim 528 \mathrm{Vac}$ |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  |  | equency Tolerance | $47 \sim 63 \mathrm{~Hz}$ |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  |  | ive Weight | $38.5 \pm 1.5 \mathrm{Kg}$ |  |  |  | $64.8 \pm 1.5 \mathrm{Kg}$ |  | $86.5 \pm 1.5 \mathrm{Kg}$ |  | $134 \pm 4 \mathrm{Kg}$ |  | 228 |  |  |  |
|  |  | ficiency（\％） | 97 | 97 | 97 | 97 | 97 | 97 | 97 | 97 | 97.5 | 97.5 | 97.5 | 97.5 | 97.5 | 97.5 |
|  |  | ooling Method | Fancooling |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  |  | aking Chopper | Frame A，B，C：built－in ；Frame D and above：optional |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  |  | Choke | Frame A，B，C：optional ；Frame D and above：built－in |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  |  | MIFilter | Optional external EMI filter is available upon purchase |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  |  | C－COP01 | VFDXXXC43A：optional；VFDXXC43E：built－in |  |  |  |  |  |  |  |  |  |  |  |  |  |
| General Specifications |  |  |  |  |  |  |  |  |  |  |  |  | ＊Availab | e in Chin | and T | wan only． |
| Control Method Pulse Width Modulated（PWM） |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| Control Mode |  |  | 1：V／F，2：$S V C, 3: V F+P G, 4: F O C+P G, 5: T Q C+P G, 6: P M+P G$ ， <br> 7：FOC sensorless，8：TQC sensorless，9：PM sensorless |  |  |  |  |  |  |  |  |  |  |  |  |  |
| Control Characteristics |  | arting Torque | Reach up to $150 \%$ or above at 0.5 Hz ．Under FOC＋PG mode，starting torque can reach $150 \%$ at 0 Hz ． |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  |  | Curve | 4－point adjustable V／f curve and square curve |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  |  | eed Response Ability | 5 Hz （vector control can reach up to 40 Hz ） |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  |  | que Limit | Normal duty $160 \%$ ，heavy duty $180 \%$ of torque current |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  | Tor | que Accuracy | $\pm 5 \%$ |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  |  | $x$ ．Output Frequency（Hz） | Normal duty：0．00～600．00Hz；Heavy duty： $0.00 \sim 300.00 \mathrm{~Hz}$ |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  |  | quency Output Accuracy | Digital command： $\pm 0.01 \%,-10^{\circ} \mathrm{C} \sim+40^{\circ} \mathrm{C}$ ，Analog command： $\pm 0.1 \%, 25 \pm 10^{\circ} \mathrm{C}$ |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  |  | tput Frequency Resolution | Digital command： 0.01 Hz ，Analog command： 0.03 Xmax ．output frequency $/ 60 \mathrm{~Hz}$（ $\pm 11 \mathrm{bit}$ ） |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  |  | erload Capacity | Normal duty：rated output current is $120 \%$ for 60 seconds， $160 \%$ for 3 seconds． Heavy duty：rated output current is $150 \%$ for 60 seconds， $180 \%$ for 3 seconds． |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  |  | quency Setting Signal | ＋10V－10，0～＋10V，4～20mA， $0 \sim 20 \mathrm{~mA}$ ，Pulse input |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  |  | cel．／decel．Time | 0．00～600．00／0．0～6000．0 Seconds |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  |  | in Control Function | Torque control，Droop control，Speed／torque control switching，Feed forward control，Zero－servo control，Momentary power loss ride thru，Speed search，Over－torque detection，Torque limit， 17 －step speed（max），Accel／decel time switch，S－curve accel／decel， 3 －wire sequence，Auto－Tuning （rotational，stationary），Dwell，Cooling fan on／off switch，Slip compensation，Torque compensation， JOG frequency，Frequency upper／lower limit settings，DC injection braking at start／stop，High slip braking，PID control（with sleep function），Energy saving control，MODOBUS communication （RS－485 RJ45，max． 115.2 kbps ），Fault restart，Parameter copy |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  |  | Control | 230 V model ：VFD150C23A（include）and series above：PMW control； <br> VFD110 C23A and series below：on／off switch control <br> 460 V model ：VFD 185 C43A（include）and series above：PMW control； <br> VFD150C43A and series below：on／off switch control |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  |  | tor Protection | Electronic thermal relay protection |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  |  | er－current tection | Over－current protection for $240 \%$ rated current current clamp『Normal duty：around 170～175\％』；『Heavy duty：around180～185\％』 |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  |  | er－voltage tection | 230：drive will stop when DC－BUS voltage exceeds 410 V <br> 460：drive will stop when DC－BUS voltage exceeds 820 V |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  |  | er－temperature Protection | Built－in temperature sensor |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  |  | Il Prevention | Stall prevention during acceleration，deceleration and running independently． |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  |  | start after Instantaneous wer Failure | Parameter setting up to 20 seconds |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  |  | ounding Leakage rrent Protection | Leakage current is higher than 50\％of the AC motor drive＇s rated current |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  |  | itifications | CE © ${ }_{\text {© }}$ us ［ |  |  |  |  |  |  |  |  |  |  |  |  |  |

## Wiring

## Wiring Diagram for Frame A~C



Note: It is not recommended to use a power capacitor or automatic power factor regulator (APFR) at the power input side. If the system requires such a device please make sure a reactor is installed between the drive and the power capacitor or APFR.

Wiring Diagram for Frame D and Frames Above
*It provides 3-phase power


## Dimensions

## Digital Keypad



KPC-CC01
Standard LCD Keypad


KPC-CE01
Optional: LCD Keypad

Frame A

MODEL
VFD007C23A VFD015C23A VFD022C23A VFD037C23A VFD007C43A/43E VFD015C43A/43E VFD022C43A/43E VFD037C43A/43E VFD040C43A/43E VFD055C43A/43E

| Frame |  | W | H | D | W1 | H1 | D1* | $\varnothing$ | $\varnothing 1$ | ø2 | $\varnothing 3$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| A1 | mm | 130.0 | 250.0 | 170.0 | 116.0 | 236.0 | 45.8 | 6.2 | 22.2 | 34.0 | 28.0 |
|  | inch | 5.12 | 9.84 | 6.69 | 4.57 | 9.29 | 1.80 | 0.24 | 0.87 | 1.34 | 1.10 |

## Frame B



MODEL
VFD055C23A
VFD075C23A
VFD110C23A
VFD075C43A/43E
VFD110C43A/43E
VFD150C43A/43E

| Frame | W | H | D | W1 | H1 | D1* | S1 | Ø1 | Ø2 | Ø3 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathbf{~ m m ~}$ | 190.0 | 320.0 | 190.0 | 173.0 | 303.0 | 77.9 | 8.5 | 22.2 | 34.0 | 28.0 |
|  | inch | 7.48 | 12.60 | 7.48 | 6.81 | 11.93 | 3.07 | 0.33 | 0.87 | 1.34 |

## Dimensions

## Frame C



## MODEL

VFD150C23A
VFD185C23A
VFD220C23A
VFD185C43A/43E
VFD220C43A/43E
VFD300C43A/43E
Unit : mm[inch]

| Frame |  | W | H | D | W1 | H1 | D1* | S1 | ¢1 | ¢2 | Ø3 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| C1 | mm | 250.0 | 400.0 | 210.0 | 231.0 | 381.0 | 92.9 | 8.5 | 22.2 | 34.0 | 50.0 |
|  | inch | 9.84 | 15.75 | 8.27 | 9.09 | 15.00 | 3.66 | 0.33 | 0.87 | 1.34 | 1.97 |

## Frame D



MODEL
FRAME D1
VFD300C23A VFD370C23A VFD550C43A VFD750C43A

FRAME_D0-1
VFD370C43S
VFD450C43S

| Frame |  | W | H | D | W1 | H1 | H2 | H3 | D1* | D2 | S1 | S2 | $\varnothing 1$ | $\varnothing 2$ | Ø3 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| D1 | mm | 330.0 | - | 275.0 | 285.0 | 550.0 | 525.0 | 492.0 | 107.2 | 16.0 | 11.0 | 18.0 | - | - | - |
|  | inch | 12.99 | - | 10.83 | 11.22 | 21.65 | 20.67 | 19.37 | 4.22 | 0.63 | 0.43 | 0.71 | - | - | - |


| Frame |  | W | H | D | W1 | H1 | H2 | H3 | D1* | D2 | S1 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| D0-1 | mm | 280.0 | - | 255.0 | 235.0 | 500.0 | 475.0 | 442.0 | 94.2 | 16.0 | 11.0 |
|  | inch | 11.02 | - | 10.04 | 9.25 | 19.69 | 18.70 | 17.40 | 3.71 | 0.63 | 0.43 |

## Dimensions

## Frame D



MODEL
FRAME_D2 VFD300C23E VFD370C23E VFD550C43E VFD750C43E

FRAME_D0-2
VFD370C43U
VFD450C43U

| Frame | W | H | D | W1 | H1 | H2 | H3 | D1* | D2 | S1 | S2 | $\varnothing 1$ | Ø2 | ø3 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| D2 mm | 330.0 | 688.3 | 275.0 | 285.0 | 550.0 | 525.0 | 492.0 | 107.2 | 16.0 | 11.0 | 18.0 | 76.2 | 34.0 | 22.0 |
| D2 inch | 12.99 | 27.10 | 10.83 | 11.22 | 21.65 | 20.67 | 19.37 | 4.22 | 0.63 | 0.43 | 0.71 | 3.00 | 1.34 | 0.87 |
| Frame | W | H | D | W1 | H1 | H2 | H3 | D1* | D2 | S1 | S2 | $\varnothing 1$ | ø2 | Ø3 |
| D0-2 mm | 280.0 | 614.4 | 255.0 | 235.0 | 500.0 | 475.0 | 442.0 | 94.2 | 16.0 | 11.0 | 18.0 | 62.7 | 34.0 | 22.0 |
| D0-2 inch | 11.02 | 21.19 | 10.04 | 9.25 | 19.69 | 18.70 | 17.40 | 3.71 | 0.63 | 0.43 | 0.71 | 2.47 | 1.34 | 0.87 |

D1*: Flange mounting

## Frame E



Detail A (Mounting Hole)


Detail B (Mounting Hole)

## MODEL

FRAME_E1
VFD450C23A
VFD550C23A
VFD750C23A
VFD900C43A
VFD1100C43A

| Frame |  | W | H | D | W1 | H1 | H2 | H3 | D1* | D2 | S1 | S2 | S3 | Ø1 | Ø2 | Ø3 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| E1 | mm | 370.0 | - | 300.0 | 335.0 | 589 | 560.0 | 528.0 | 143.0 | 18.0 | 13.0 | 13.0 | 18.0 | - | - | - |
|  | inch | 14.57 | - | 11.81 | 13.19 | 23.19 | 22.05 | 20.80 | 5.63 | 0.71 | 0.51 | 0.51 | 0.71 | - | - | - |

## Dimensions

## Frame E



MODEL
FRAME_E2
VFD450C23E VFD550C23E VFD750C23E VFD900C43E
VFD1100C43E

| Frame |  | W | H | D | W1 | H1 | H2 | H3 | D1* | D2 | S1 | S2 | S3 | Ø1 | Ø2 | Ø3 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| E2 | mm | 370.0 | 715.8 | 300.0 | 335.0 | 589 | 560.0 | 528.0 | 143.0 | 18.0 | 13.0 | 13.0 | 18.0 | 22.0 | 34.0 | 92.0 |
|  | inch | 14.57 | 28.18 | 11.81 | 13.19 | 23.19 | 22.05 | 20.80 | 5.63 | 0.71 | 0.51 | 0.51 | 0.71 | 0.87 | 1.34 | 3.62 |

## Frame F



MODEL
FRAME_F
VFD900C23A
VFD1320C43A
VFD1600C43A

| Frame |  | W | H | D | W1 | H1 | H2 | H3 | D1* | D2 | S1 | S2 | S3 | Ø1 | Ø2 | Ø3 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| F1 | mm | 420.0 | - | 300.0 | 380.0 | 800.0 | 770.0 | 717.0 | 124.0 | 18.0 | 13.0 | 25.0 | 18.0 | 92.0 | 35.0 | 22.0 |
|  | inch | 16.54 | - | 11.81 | 14.96 | 31.50 | 30.32 | 28.23 | 4.88 | 0.71 | 0.51 | 0.98 | 0.71 | 3.62 | 1.38 | 0.87 |

## Dimensions

## Frame F



MODEL
FRAME_F2
VFD900C23E
VFD1320C43E
VFD1600C43E

## Unit : mm[inch]

| Frame | W | H | D | W1 | H1 | H2 | H3 | D1* | D2 | S1 | S2 | S3 | Ø1 | Ø2 | Ø3 |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| F2 | mm | 420.0 | 940.0 | 300.0 | 380.0 | 800.0 | 770.0 | 717.0 | 124.0 | 18.0 | 13.0 | 25.0 | 18.0 | 92.0 | 35.0 | 22.0 |
|  | inch | 16.54 | 37.00 | 11.81 | 14.96 | 31.50 | 30.32 | 28.23 | 4.88 | 0.71 | 0.51 | 0.98 | 0.71 | 3.62 | 1.38 | 0.87 |

## Frame G



Detail A (Mounting Hole)
Detail B (Mounting Hole)

MODEL
FRAME_G1
VFD1850C43A
VFD2200C43A

| Frame |  | W | H | D | W1 | H1 | H2 | H3 | S1 | S2 | S3 | $\varnothing 1$ | ø2 | ø3 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| G1 | mm | 500.0 | - | 397.0 | 440.0 | 1000.0 | 963.0 | 913.6 | 13.0 | 26.5 | 27.0 | - | - | - |
|  | inch | 19.69 | - | 15.63 | 217.32 | 39.37 | 37.91 | 35.97 | 0.51 | 1.04 | 1.06 | - | - | - |

## Dimensions

## Frame G




Detail A (Mounting Hole)


Detail B (Mounting Hole)

MODEL
FRAME_G2
VFD1850C43E
VFD2200C43E

| Frame |  | W | H | D | W1 | H1 | H2 | H3 | S1 | S2 | S3 | $\varnothing 1$ | Ø2 | Ø3 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| G2 | mm | 500.0 | 1240.2 | 397.0 | 440.0 | 1000.0 | 963.0 | 913.6 | 13.0 | 26.5 | 27.0 | 22.0 | 34.0 | 117.5 |
|  | inch | 19.69 | 48.83 | 15.63 | 217.32 | 39.37 | 37.91 | 35.97 | 0.51 | 1.04 | 1.06 | 0.87 | 1.34 | 4.63 |

## Frame H



See Detail A(Mounting Hole)
See Detail B(Mounting Hole)

## MODEL

FRAME_H1
VFD2800C43A
VFD3150C43A
VFD3550C43A
VFD4500C43A*
Unit : mm[inch]

| Frame |  | W | H | D | W1 | W2 | W3 | W4 | W5 | W6 | H1 | H2 | H3 | H4 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| H1 | mm | 700.0 | 1435.0 | 398.0 | 630.0 | 290.0 | - | - | - | - | 1403.0 | 1346.6 | - | - |
|  | inch | 27.56 | 56.50 | 15.67 | 24.80 | 11.42 | - | - | - | - | 55.24 | 53.02 | - | - |
| Frame |  | H5 | D1 | D2 | D3 | D4 | D5 | D6 | S1 | S2 | S3 | $\varnothing 1$ | $\varnothing 2$ | $\varnothing 3$ |
| H1 | mm | - | 45.0 | - | - | - | - | - | 13.0 | 26.5 | 25.0 | - | - | - |
|  | inch | - | 1.77 | - | - | - | - | - | 0.51 | 1.04 | 0.98 | - | - | - |

## Dimensions

## Frame H



## Frame H



MODEL
FRAME_H3
VFD2800C43E
VFD3150C43E
VFD3550C43E
VFD4500C43E*
Unit: mm[inch]

| Frame |  | W | H | D | W1 | W2 | W3 | W4 | W5 | W6 | H1 | H2 | H3 | H4 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| H3 | mm | 700.0 | 1745.0 | 404.0 | 630.0 | 500.0 | 630.0 | 760.0 | 800.0 | - | 1729.0 | 1701.6 | - | - |
|  | inch | 27.56 | 68.70 | 15.91 | 24.80 | 19.69 | 24.80 | 29.92 | 31.50 | - | 68.07 | 66.99 | - | - |
| Frame |  | H5 | D1 | D2 | D3 | D4 | D5 | D6 | S1 | S2 | S3 | Ø1 | $\varnothing 2$ | Ø3 |
| H3 | mm | - | 51.0 | 38.0 | 65.0 | 204.0 | 68.0 | 137.0 | 13.0 | 26.5 | 25.0 | 22.0 | 34.0 | 117.5 |
|  | inch | - | 2.01 | 1.50 | 2.56 | 8.03 | 2.68 | 5.39 | 0.51 | 1.04 | 0.98 | 0.87 | 1.34 | 4.63 |

## Option Cards

EMC-PG01L


Set by Pr.10-00~10-02

| Terminals |  | Descriptions |
| :---: | :---: | :---: |
| PG1 | VP | Output voltage for power: $+5 \mathrm{~V} /+12 \mathrm{~V} \pm 5 \%$ (use FSW3 to switch $+5 \mathrm{~V} /+12 \mathrm{~V}$ ) Max. output current: 200mA |
|  | DCM | Common for power and signal |
|  | $\begin{aligned} & \mathrm{A} 1, \mathrm{~A} 1 \text {,B1, /B1, } \\ & \text { Z1, /Z1 } \end{aligned}$ | Encoder input signal (Line Driver) <br> It can be 1-phase or 2-phase input; Max. input frequency: 300kP/sec |
| PG2 | $\begin{aligned} & \text { A2, IA2, B2, I } \\ & \text { B2 } \end{aligned}$ | Pulse input signal (Line Driver or Open Collector) <br> Open collector input: $+5 \mathrm{~V} /+12 \mathrm{~V}$ (Note1) <br> It can be 1-phase or 2-phase input; Max. input frequency: $300 \mathrm{kP} / \mathrm{sec}$. |
| PG OUT | AO, IAO, BO, IBO, ZO, IZO , SG | PG card output signals. It has division frequency function: 1~255 times Max. output voltage for Line driver: 5 Vdc <br> Max. output current: 50 mA ; Max. output frequency: $300 \mathrm{kP} / \mathrm{sec}$ <br> SG: The GND of PG card is the same as the host controller or PLC, so a common output signal is attained. |

EMC-PG010

|  | Terminals |  | Descriptions |
| :---: | :---: | :---: | :---: |
|  | PG1 | VP | Output voltage for power: $+5 \mathrm{~V} /+12 \mathrm{~V} \pm 5 \%$ (use FSW 3 to switch $+5 \mathrm{~V} /+12 \mathrm{~V}$ ) Max. output current: 200mA |
|  |  | DCM | Common for power and signal |
|  |  | A1, IA1 ,B1, /B1, Z1, IZ1 | Encoder input signal (Line Driver or Open Collector) <br> Open collector input: $+5 \mathrm{~V} /+12 \mathrm{~V}$ (Note1) <br> It can be 1-phase or 2-phase input; Max. input frequency: 300kP/sec |
|  | PG2 | $\begin{aligned} & \text { A2, IA2, B2, I } \\ & \text { B2 } \end{aligned}$ | Pulse input signal (Line Driver or Open Collector) <br> Open collector input: $+5 \mathrm{~V} /+12 \mathrm{~V}$ (Note1) <br> It can be 1-phase or 2-phase input; Max. input frequency: $300 \mathrm{kP} / \mathrm{sec}$. |
| $\begin{aligned} & \text { Set by } \\ & \text { Pr.10-00~10-02 } \end{aligned}$ | PG OUT | V+, /V- | Needs external power source for PG OUT circuit. Input voltage of power:+12V ~+24V |
|  |  | V - | Negative power supply input |
|  |  | A/O, B/O, ZO, | PG card output signals. It has division frequency function: 1~255 times Add a pull-up resistor to the open collector output signals to avoid signal interferences. [Three pull-up resistors are included in the package ( $1.8 \mathrm{k} \Omega / 1 \mathrm{~W}$ )] Max. Output current: 20mA; Max output frequency: $300 \mathrm{KP} / \mathrm{Sec}$ |

EMC-PG01R

|  | Terminals |  | Descriptions |
| :---: | :---: | :---: | :---: |
|  |  | R1-R2 | Resolver output power 7Vrms, 10kHz |
|  | PG1 | $\begin{aligned} & \text { S1,S2, S3, } \\ & \text { S4, } \end{aligned}$ | Resolver input signal $3.5 \pm 0.175 \mathrm{Vrms}, 10 \mathrm{kHz}$ |
|  | PG2 | $\begin{aligned} & \text { A2, IA2, B2, I } \\ & \text { B2 } \end{aligned}$ | Pulse input signal (Line Driver or Open Collector) <br> Open collector input: $+5 \mathrm{~V} /+12 \mathrm{~V}$ (Note1) <br> It can be 1-phase or 2-phase input; Max. input frequency: 300kP/sec. |
| Set by Pr.10-00~10-02 | PG OUT | $\begin{aligned} & \text { AO, IAO, } \\ & \text { BO, /BO, } \\ & \text { ZO, IZO , SG } \end{aligned}$ | PG card output signals. It has division frequency function: 1~255 times <br> Max. output voltage for Line driver: 5Vdc <br> Max. output current: 50mA <br> Max. output frequency: $300 \mathrm{kP} / \mathrm{sec}$ <br> SG: The GND of PG card is the same as the host controller or PLC, <br> so a common output signal is attained. |

EMC－PG01U
■ FJMP1 S：Standard UVW Output Encoder；D：Delta Encoder


Note 1：For the Open Collector，set input voltage to $5 \sim 15 \mathrm{~mA}$ and install a pull－up resistor
【5V】 Recommend pull－up resistor： $100 \sim 220 \Omega, 1 / 2 \mathrm{~W}$ and above
【12V】Recommend pull－up resistor： $510 \sim 1.35 \mathrm{k} \Omega, 1 / 2 \mathrm{~W}$ and above
【24V】Recommend pull－up resistor： $1.8 \mathrm{k} \sim 3.3 \mathrm{k} \Omega, 1 / 2 \mathrm{~W}$ and above

## Screw Specifications for Option Card Terminals

| EMC－D42A／EMC－D611A | Wire gauge |
| :--- | :--- |
| EMC－BPS01 | Torque |
| EMC－R6AA | Wire gauge |
|  | Torque |
| EMC－PG01L／EMC－PG01O | Wire gauge |
| EMC－PG01R／EMC－PG01U | Torque |

24～12AWG $\left(0.205 \sim 3.31 \mathrm{~mm}^{2}\right)$
$4 \mathrm{Kg}-\mathrm{cm}[3.47 \mathrm{lb}-\mathrm{in}]$
$24 \sim 16 \mathrm{AWG}\left(0.205 \sim 1.31 \mathrm{~mm}^{2}\right)$
$6 \mathrm{Kg}-\mathrm{cm}[5.21 \mathrm{lb}-\mathrm{in}]$
$30 \sim 16 \mathrm{AWG}\left(0.0509 \sim 1.31 \mathrm{~mm}^{2}\right)$
$2 \mathrm{Kg}-\mathrm{cm}[1.74 \mathrm{lb}-\mathrm{in}]$


## Option Cards

EMC-D42A

|  | Terminals | Descriptions |
| :---: | :---: | :---: |
|  | COM | Common for multi-function input terminals <br> Select SINK (NPN) / SOURCE (PNP) in J1 jumper / external power supply |
|  | MI10~ MI13 | Refer to parameters 02-26~02-29 to program the multi-function inputs MI10~MI13. Internal power is applied from terminal E24: $+24 \mathrm{Vdc} \pm 5 \% 200 \mathrm{~mA}$, 5 W External power +24 Vdc : max. voltage 30 Vdc , min. voltage 19 Vdc , 30 W ON : the activation current is 6.5 mA ; OFF: leakage current tolerance is $10 \mu \mathrm{~A}$ |
| 1/O Extension Card | M010~MO11 | Multi-function output terminals (photocoupler) Duty-cycle: 50\%; Max. output frequency: 100 Hz Max. current: 50mA; Max. voltage: 48 Vdc |
|  | MXM | Common for multi-function output terminals MO10, MO11 (photocoupler) Max 48 Vdc 50 mA |

EMC-D611A


I/O Extension Card

| Terminals | Descriptions |
| :--- | :--- |
| AC | AC power common for multi-function input terminal (Neutral) |
| MI10~Mi15 | Refer to Pr. $02.26 \sim$ Pr. 02.31 for multi-function input selection <br> Input voltage: $100 \sim 130 \mathrm{VAC} ;$ Input frequency: $57 \sim 63 \mathrm{~Hz}$ <br> Input impedance: 27 Kohm |
| Terminal response time: ON: $10 \mathrm{~ms} ;$ OFF: 20 ms |  |

EMC-R6AA


Relay
Extension Card

## Terminals Descriptions

Refer to Pr. $02.36 \sim$ Pr. 02.41 for multi-function input selection Resistive load: 3A(N.O.)/250VAC
RA10~RA15 5A(N.O.)/30Vdc
RC10~RC15 Inductive load (COS 0.4)
2.0A(N.O.)/250VAC
2.0A(N.O.)/30Vdc

It is used to output each monitor signal, such as for drive in operation, frequency attained or overload indication.

EMC-BPS01


Power Shift Card

| Terminals | Descriptions |
| :---: | :---: |
|  | When the AC motor drive power is off, the external power supply card provides external power to the network system, PLC function, and other functions to allow continued operations. |
| 24V | Input power: $24 \mathrm{~V} \pm 5 \%$ |
| GND | Maximum input current: 0.5A |
|  | Note: (1) Do not connect the control terminal +24 V (Digital control signal common: SOURCE) directly to the EMC-BPS01 input terminal 24 V <br> (2) Do not connect control terminal GND directly to the EMC-BPS01 input terminal GND. |

CMC-MOD01


Features

- MDI/MDI-X auto-detect
- Virtual serial port.
- Supports MODBUS TCP protocol
- AC motor drive keypad/Ethernet configuration

Network Interface

| Interface | RJ-45 with Auto MDI/MDIX | Transmission speed | 10/100 Mbps Auto-Detect |
| :--- | :--- | :--- | :--- |
| Number of ports | 1 Port | Network protocol | ICMP, IP, TCP, UDP, DHCP, SMTP, |
| Transmission method | IEEE 802.3, IEEE 802.3u |  | MODBUS OVER TCP/IP, <br> Delta Configuration |
| Transmission cable | Category 5e shielding 100M |  |  |

## CMC-EIP01



## Features

- MDI/MDI-X auto-detect ■ Virtual serial port
- Supports MODBUS TCP and Ethernet/IP protocol
- Baud rate: 10/100Mbps auto-detect
- AC motor drive keypad/Ethernet configuration

Network Interface

| Interface | RJ-45 with Auto MDI/MDIX | Transmission speed | 10/100 Mbps Auto-Detect |
| :--- | :--- | :--- | :--- |
| Number of ports | 1 Port | Network protocol | ICMP, IP, TCP, UDP, DHCP, SMTP, |
| Transmission method | IEEE 802.3, IEEE 802.3u |  | MODBUS OVER TCP/IP, <br> Dransmission cable |
| Category 5e shielding 100 M |  |  |  |

## CMC-PD01



Features
■ Supports PZD control data exchange

- Supports PKW polling AC motor drive parameters
- Supports user diagnosis function

■ Auto-detects baud rates; supports Max. 12Mbps

PROFIBUS DP Connector
Interface
Transmission method
Transmission cable
Electrical isolation

DB9 connector
High-speed RS-485
Shielded twisted pair cable 500VDC

## Communication

| Message type | Cyclic data exchange |
| :--- | :--- |
| Module name | CMC-PD01 |
| GSD document | DELA08DB.GSD |
| Company ID | 08DB (HEX) |
| Serial transmission <br> speed supported <br> (auto-detection) | 9.6kbps; $19.2 \mathrm{kbps} ; 93.75 \mathrm{kbps} ; 187.5 \mathrm{kbps} ; 125 \mathrm{kbps} ;$ |

## CMC-DN01

## Features

- Based on the high-speed communication interface of Delta HSSP protocol, able to conduct immediate control of AC motor drive.

- Supports Group 2 only connection and polling I/O data exchange.
- For I/O mapping, supports Max. 32 words of input and 32 words of output.
- Supports EDS file configuration in DeviceNet configuration software.

■ Supports all baud rates on DeviceNet bus: 125kbps, 250kbps, 500kbps and extendable serial transmission speed mode.

- Node address and serial transmission speed can be set up on AC motor drive.
- Power supplied from AC motor drive.


## DeviceNet Connector

| Interface | 5-PIN open removable connector. Of 5.08 mm PIN interval |
| :---: | :---: |
| Transmission method | CAN |
| Transmission cable | Shielded twisted pair cable (with 2 power cables) |
| Transmission speed | $125 \mathrm{kbps}, 250 \mathrm{kbps}$, 500 kbps and extendable serial transmission speed mode |
| Network protocol | DeviceNet protocol |

## AC Motor Drive Connection Port

| Interface | 50 PIN communication terminal |
| :--- | :--- |
| Transmission method | SPI communication |
| Terminal function | 1. Communicating with AC motor drive |
| Communication protocol | Delta HSSP protocol |

## Option Cards

## EMC-COP01

Built-in EMC-COP01 card are available for VFD___C23E and VFD___C43E.

> RJ-45 Pin definition



8~1
Male


Female

| Pin | Pin name |
| :---: | :--- |
| 1 | CAN_H |
| 2 | CAN_L |
| 3 | CAN_GND |
| 6 | CAN_GND |

Definition
CAN_H bus line (dominant high) CAN_L bus line (dominant low) Ground/OV/V-Ground/OV/V-

Network Interface

| Interface | RJ-45 |
| :--- | :--- |
| Number of ports | 1 Port |
| Transmission method | CAN |
| Transmission cable | CAN standard cable |
| Transmission speed | 1M 500k 250k 125k 100k 50k |
| Communication protocol | CANopen |

## CANopen Communication Cable

Model: TAP-CB05, TAP-CB10


| Titie | Part No. | L |  |
| :---: | :---: | :---: | :---: |
|  |  | mm | inch |
| 1 | TAP-CB05 | $500 \pm 10$ | $19 \pm 0.4$ |
| 2 | TAP-CB10 | $1000 \pm 10$ | $39 \pm 0.4$ |

Digital Keypad Accessories: RJ45 Extension Leads and CMC-EIP01 Cables
Applicable Models: CBC-K3FT, CBC-K5FT, CBC-K7FT, CBC-K10F, CBC-K16FT

| Title | Part No. |  |
| :---: | :---: | :--- | :--- |
| 1 | CBC-K3FT | Explanation |
| 2 | CBC-K5FT | RJ45 extension lead, 3 feet (approximately 0.9 m ) |
| 3 | CBC-K7FT | RJ45 extension lead, 5 feet (approximately 1.5 m ) |
| 4 | CBC-K10FT | RJ45 extension lead, 7 feet (approximately 2.1 m ) |
| 5 | CBC-K16FT | RJ45 extension lead, 10 feet (approximately 3 m ) |

## Model Name



Applicable Motor Capacity
007:1HP (0.75kW)~3550:475HP (355kW)
Refer to the specifications for details
Series name (Variable Frequency Drive)

## Ordering information



Power Range
230V:
ND: $0.75 \sim 3.7 \mathrm{~kW}$
HD: $0.4 \sim 2.2 \mathrm{~kW}$
460V:
ND: $0.75 \sim 5.5 \mathrm{~kW}$
HD: $0.4 \sim 4.0 \mathrm{~kW}$
VFD007C23A
VFD015C23A
VFD022C23A
VFD037C23A

## Models

VFD055C23A
VFD075C23A
VFD110C23A

| VFD007C43A | VFD007C43E |
| :--- | :--- |
| VFD015C43A | VFD015C43E |
| VFD022C43A | VFD022C43E |
| VFD037C43A | VFD037C43E |
| VFD040C43A | VFD040C43E |
| VFD055C43A | VFD055C43E |

## 230V:

ND: $5.5 \sim 11 \mathrm{~kW}$
HD: 3.7~7.5kW

## 460V: <br> ND: $7.5 \sim 15 \mathrm{~kW}$ <br> HD: 5.5~11kW


230V:
ND: 15~22kW

HD: 11~18.5kW

## 460 V :

ND: 18.5~30kW
HD: 15~22kW


## 230V:

ND: $30 \sim 37 \mathrm{~kW}$
HD: 20~30kW

## 460V:

ND: 37~75kW
HD: $30 \sim 45 \mathrm{~kW}$


230V:
ND: 45~75kW
HD: 37~55kW
460 V :
ND: 90~110kW HD: 55~90kW


## 230V:

ND: 90kW
HD: 75kW

## 460 V :

ND: 132~160kW HD: 110~132kW


## 460V:

ND: 185~220kW
HD: 160~185kW

460V:
ND: 280~450kW
HD: 220~355kW

[^1]
## Frame_G1

VFD1850C43A VFD2200C43A

> VFD300C23A VFD370C23A VFD550C43A VFD750C43A

Frame_D1

Frame_E1 VFD450C23A VFD550C23A VFD750C23A VFD900C43A VFD1100C43A

Frame_F1 VFD900C23A VFD1320C43A VFD1600C43A

ND: 280~450kW
HD: 220~355kW
$\begin{array}{lll}\text { VFD150C23A } & \text { VFD185C43A } & \text { VFD185C43E } \\ \text { VFD185C23A } & \text { VFD220C43A } & \text { VFD220C43E }\end{array}$ VFD220C23A VFD300C43A VFD300C43E

Frame_D0-1 Frame_D2
VFD370C43S VFD300C23E VFD450C43S VFD370C23E VFD550C43E VFD750C43E

Frame D0-2
VFD370C43U VFD450C43U

Frame_G2 VFD1850C43E VFD2200C43E

| Frame_H2 | Frame_H3 |
| :--- | :--- |
| VFD2800C43E-1 | VFD2800C43E |
| VFD3150C43E-1 | VFD3150C43E |
| VFD3550C43E-1 | VFD3550C43E |
| VFD4500C43E-1* | VFD4500C43E* |

VFD2800C43E-1 VFD3550C43E-1 VFD4500C43E-1*

Frame_H3
VFD2800C43E VFD3550 VFD4500C43E*

[^2]
## Standard Motors

Used with 400V Standard Motors It is recommended to add an AC output reactor when using with a 400 V standard motor to prevent damage to motor insulation.

Torque Characteristics and
Temperature Rise
When a standard motor is drive controlled, the motor temperature will be higher than with DOL operation.
Please reduce the motor output torque when operating at low speeds to compensate for less cooling efficiency.
For continuous constant torque at low speeds, external forced motor cooling is recommended.

## Vibration

When the motor drives the machine, resonances may occur, including machine resonances. Abnormal vibration may occur when operating a 2 -pole motor at 60 Hz or higher.

## Noise

When a standard motor is drive controlled, the motor noise will be higher than with DOL peration
To lower the noise, please increase the carrier frequency of the drive. The motor fan can be very noisy when the motor speed exceeds 60 Hz

## Special Motors

High-speed Motor
o ensure safety, please try the frequency setting with another motor before operating the high-speed motor at 120 Hz or higher.

Explosion-proof Motor
Please use a motor and drive that comply with explosion-proof requirements

Submersible Motor \& Pump
The rated current is higher than that of a tandard motor.
Please check before operation and select the capacity of the AC motor drive carefully. The motor temperature characteristics diffe from a standard motor, please set the moto thermal time constant to a lower value.

## Brake Motor

When the motor is equipped with a mechanica brake, the brake should be powered by the mains supply.
Damage may occur when the brake is powered by the drive output. Please DO NOT drive the motor with the brake engaged

## Gear Motor

In gearboxes or reduction gears, lubrication may be reduced if the motor is continuously operated at low speeds.
Please DO NOT operate in this way.
Synchronous Motor
These motors need suitable software for control. Please contact Delta for more information.

Single-phase Motor
Single-phase motors are not suitable for being operated by an AC Motor Drive. Please use a 3-phase motor instead when necessary

## Attention <br> Attention

## Environmental Conditions

Installation Position

1. The drive is suitable for installation in a place with ambient temperature from -10 to 50 J
2. The surface temperature of the drive and brake resistor will rise under specific operation conditions. Therefore, pleas install the drive on materials that are noncombustible.
3. Ensure that the installation site complies with the ambient conditions as stated in the manual

## Wiring

Limit of Wiring Distance
For the remote operation, please use
twist-sive and control box she distance between 20 m .

Maximum Motor Cable Length
current peaks due to
stray capacitance.
Please ensure that the motor cable is less than 30 m .
If the cable length can't be reduced, please lower the carrier frequency or use an AC reactor
Choose the Right Cable
Please refer to current value to choose the right cable section with enough capacity or use recommended cables.

Grounding
Please ground the drive completely by using the grounding terminal

## How to Choose the Drive Capacity

## Standard Motor

Please select the drive according to applicable motor rated current listed in the drive specification.
Please select the next higher power AC drive in case higher starting torque or quick acceleration/deceleration is needed.

## Special Motor

Please select the drive according to: Rated current of the drive > rated current of the moto

Transportation and Storage
Please transport and store the drive in a place that meets environment specifications.

## Peripheral Equipment

## Molded-Case Circuit Breakers

(MCCB)
instal the recommended MCCB or ELCB in the main circuit of the drive and make sure tha the capacity of the breaker is equal to or lower than the recommended one.

Add a Magnetic Contactor(MC) in
the Output Circuit
When a MC is installed in the output circuit of the drive to switch the motor to commercial power or other purposes, please make sure that the drive and motor are completely stopped and remove the surge absorbers from the MC before switching it.
Add a Magnetic Contactor (MC) in the Input Circuit
Please only switch the MC ONCE per hour or it may damage the drive. Please use RUN/STOP signal to switch many times during motor operation

## Motor Protection

The thermal protection function of the drive can be used to protect the motor by setting the operation level and motor type
When using a high-speed motor or
water-cooled motor the thermal time constant should be set to a lower value.

When using a longer cable to connect the motor thermal relay to a motor, high-frequency currents may enter via the stray capacitance.
It may result in malfunctioning of the relay as the real current is lower than the setting of therm carrier frequency or add an AC reactor to solve carrier frequency or add an AC reactor to solve this.

DO NOT Use Capacitors to Improve the Power Factor
Use a DC reactor to improve the power factor of the dre. pleas factor drive to prevent motor faults due to over current

Do NOT Use Surge Absorber
Please DO NOT install surge absorbers on the output circuit of the drive.

Lower the Noise
To ensure compliance with EMC regulations usually a filter and shielded wiring is used to lower the noise.

## Method Used to Reduce the Surge

Current
Surge currents may occur in the phase-lead capacitor of the power system, causing an overvoltage when the drive is stopped or at low loads.

It is recommended to add a DC reactor to the drive.

## Leading the Future of Drive Techinology

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Smarter. Greener. Together.

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[^0]:    ${ }^{*}$ Note: Please refer to the Product Specification

[^1]:    Frame_H1 VFD2800C43A VFD3150C43A VFD3550C43A VFD4500C43A*

[^2]:    * Available in China and Taiwan only.

